

NAVAL POSTGRADUATE SCHOOL Monterey, California





THESIS

AN ANALYSIS OF THREE APPROACHES TO THE HELICOPTER PRELIMINARY DESIGN PROBLEM

by

Allen C. Hansen

March 1984

Thesis Advisor:

D. M. Layton

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An Analysis of Three Approaches to the Helicopter Preliminary Design Problem

by

Allen C. Hansen Lieutenant, United States Navy B.A., University of Pennsylvania, 1976

Submitted in partial fulfillment of the requirements for the degree of

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Author:	all C. Han
Approved by:	Coned may to
••	Thesis Advisor
	Chairman, Department of Aeronautics
	Chairman, Department of Aeronautics
	AM DHU
	Dean of Science and Engineering

ABSTRACT

Three methodologies from which to approach the problem of preliminary helicopter design are explored in this paper. The first is a sensitivity analysis of the basic helicopter performance equations. The purpose here is to ascertain where reasonable simplifications can be made that do not seriously degrade the accuracy of the results. The second is a graphical parametric design method, known as Carpet Plots. In this method a graphical solution is developed to meet the design criteria of the helicopter. In the third, an overview of Boeing Vertol's Helicopter Sizing and Performance Computer Program is given. The computer routines which enable a person to access HESCOMP on the Naval Postgraduate School main frame IBM system are also provided.

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I. INTRODUCTION

A. GENERAL

The helicopter design process, the subject of numerous articles and studies is an evolving discipline that borders on being an art. A successful design must balance the user's needs and desires against practical capabilities.

With the introduction of composite materials and new technologies, principally in rotor and engine performance, significant advances have been made in helicopter capabilities. In some instances, the performances of hybrid helicopter designs rivals that of a similarly sized conventional aircraft. For example, the YVX, a joint Boeing-Bell venture, will have the hover and low speed capabilities of a helicopter while being able to cruise at 300 knots.

Viable commercial and military helicopter designs are only thirty years old. The first major use of helicopters occurred during the Korean conflict. To put this in perspective, the first large scale use of conventional type aircraft was in World War I.

Helicopter design can proceed on a number of different levels, ranging from comprehensive computer design programs to preliminary analysis using simplifications of the basic performance equations. Each has its merit and place.

Computer-aided design provides a great deal of data.

Generally, these programs integrate aircraft configuration sizing, performance and weight calculations in an iterative process. An example of a computer design program for helicopters is the Helicopter Sizing and Performance Computer Program [HESCOMP], originally developed by Boeing-Vertol for NASA. This program is currently used as a wide number of institutions conducting studies in helicopter design.

On the opposite end of the spectrum would be sensitivity design studies using the performance equations. Surprisingly accurate simplications of these equations can be made. This provides the designer with an excellent method for doing first cut preliminary helicopter sizing at a low cost.

B. OBJECTIVE

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This report is an investigation of several of the methods employed in the preliminary design of a helicopter. Conceptually, the report can be divided into three parts. In the first section, a sensitivity analysis of the basic performance equations is performed. The purpose here is to ascertain where reasonable simplications can be made that do not seriously degrade the accuracy of the result.

In the second section a graphical method of doing parametric design studies, known as Carpet Plots, is developed. This method allows the user to formulate a graphical solution matrix to meet the design criteria specified for the helicopter. Carpet Plots are

particularly instructive since they give visual insight into the interplay of the various design parameters.

In the last section, an overview of HESCOMP is given.

Programs are developed which enable a person to access

HESCOMP on the Naval Postgraduate School Main Frame IBM system.

II. SENSITIVITY ANALYSES OF BASIC HELICOPTER EQUATIONS

A. DESCRIPTION OF PROBLEM

In preliminary helicopter design, there are a number of instances where a quick first cut analysis would be extremely helpful. This is especially true in determining the preliminary size of the helicopter required to meet the specifications.

Historically, there are a number of variables in the performance equations of helicopters which may be treated as constants. This may allow for significant simplifications and aid in the preliminary design process.

In this section, a sensitivity analysis of the performance equations is done. In a sensitivity analysis, each parameter [or variable] is varied in order to determine its effect on the equation. Variables which are shown to have little effect may be treated as constants and the equation simplified accordingly.

B. SOLIDITY

Solidity, σ , is the fraction of the disk area that is composed of blades. It is a function of b, the number of blades, of a constant cord, c, at a radius, R:

$$\sigma = \frac{bc}{\pi R} \tag{2.1}$$

C. DISK LOADING:

Disk loading is defined as the ratio of the weight to the total area of the rotor disk.

DL =
$$\frac{\text{WEIGHT}}{\text{AREA}}$$

$$= \frac{\text{W}}{\text{A}} = \frac{\text{W}}{\pi R^2} [1b/\text{ft}^2]$$
(2.2)

D. POWER LOADING

Power loading is the ratio of weight to input power.

$$PL = \frac{W}{P_{in}} [1b/hp] \qquad (2.3)$$

In a hover, thrust equals weight; this allows us to rewrite the power loading for the hover condition as

$$PL = \frac{T}{P_{in}} = \frac{ROTOR\ THRUST}{ROTOR\ HORSEPOWER} [1b/hp]$$
 (2.4)

E. COEFFICIENT OF THRUST AND POWER

The coefficient of thrust, C_{T} , is a non-dimensional coefficient which facilitates computations and comparisons:

$$C_{T} = \frac{T}{A\rho V_{T}^{2}} = \frac{T}{\pi R^{2} \rho (\Omega R)^{2}}$$
 (2.5)

Similarly, a coefficient of power, $C_{\mathbf{p}}$, has been established as:

$$C_p = \frac{P}{A\rho V_T^3} = \frac{P}{\pi R^2 \rho (\Omega R)^3}$$
 (2.6)

No significant simplifications can be made to either of these coefficients. However, it should be observed that the coefficient of thrust is inversely proportional to the square of the rotor tip velocity, while the coefficient of power is inversely proportional to the cube.

Assuming all other factors being equal, increasing the rotor tip velocity from 600 fps to 700 fps [an increase of 16.7 percent] will have the following result on these coefficients.

$$C_{T} = \frac{T}{A\rho V_{T}^{2}}$$

$$= \frac{T}{A\rho (1.167)^{2}}$$

$$= \frac{T}{A\rho (1.361)}$$
(2.5)

The coefficient of thrust is reduced by 26.9 percent. Similarly, for the coefficient of power:

$$C_{p} = \frac{P}{A\rho V_{T}^{3}}$$

$$= \frac{P}{A\rho (1.167)^{3}}$$

$$= \frac{P}{A\rho (1.589)}$$
(2.6)

The coefficient of power is reduced by 37.1 percent.

F. HOVER POWER

The total power in a hover is made up of two terms, profile power, P_{o} , and induced power, P_{i} .

Utilizing black element theory the profile power required to hover can be expressed as:

$$P_o = \frac{1}{8} \sigma_r \overline{C}_{do} \rho A(\Omega R)^3 \qquad (2.7)$$

The induced power predicted by momentum theory is:

$$P_{i} = V_{in} T$$

$$= \frac{T^{3/2}}{\sqrt{2\pi \rho R^{2}}}$$
(2.8)

The total power required to hover is:

$$P_{T} = P_{i} + P_{o} \tag{2.9}$$

$$P_{T} = \frac{T^{3/2}}{\sqrt{2\pi \rho R^{2}}} + \frac{1}{8} \sigma_{T} C_{do} \rho A(\Omega R)^{3}$$
 (2.10)

Donald M. Layton in <u>Helicopter Performance</u>, [Ref. 1], found that for the optimum hover power, the induced power is equal to twice the profile power. The analysis was performed in the following manner.

By assuming constant weight, density, solidity, and an average profile drag coefficient, as well as a fixed rotational velocity, equation (2.10) reduces to

$$P = \frac{C_1}{R} + C_2 R^2 \tag{2.11}$$

where C_1 and C_2 are constants.

As equation (2.12) shows, profile power increases as the square of the blade radius while the induced power decreases with increasing blade radius.

The optimum hover power with respect to rotor radius can be determined by taking the differential and setting it equal to zero.

$$\frac{dP}{dR} = 0 = -\frac{C_1}{R_2} + 2 C_2 R \qquad (2.12A)$$

or $\frac{C_1}{R} = 2 C_2 R^2$ (2.12B)

which implies $P_i = 2 P_o$ (2.12C)

G. HELICOPTER SIZING

A simplified relationship between the total power required, gross weight and rotor radius can be developed in the following manner.

The total power required to hover equation for the main rotor was developed in the preceding section and is repeated here for clarity.

$$P_{T} = P_{i} + P_{o} \tag{2.9}$$

$$P_{T} = \frac{T^{3/2}}{\sqrt{2\pi\rho}} \cdot \frac{1}{R} + \frac{1}{8} \sigma_{r} \overline{C}_{do} \rho \pi V_{tip}^{3} R^{2}$$
 (2.10)

In a hover, thrust equals weight. Solving equation (2.11) for weight one obtains:

$$W^{3/2} = [P_T - \frac{1}{8} \sigma C_{do} \rho \pi V_T^3 R^2] \sqrt{\rho A}$$
 (2.13)

This equation may be further simplified if it is assumed that the density, average profile drag coefficient and tip velocity are constants; these are reasonable assumptions. Historically, the average profile drag coefficient of a helicopter has been approximately 0.01. The operating environment of today's helicopters, especially military, is below 5,000 feet agl. This allows for the use of the standard sea level value for density with little error. Primarily, due to tip mach effects, the upper limit on the rotor tip velocity is in the range of 700 fps.

The resulting equation with these assumptions incorporated into a constant, K, is:

$$W = [47.527 P_T R - K_1 bc]^{2/3}$$
 (2.13)

Equation (2.13) can be further reduced when the order of magnitude of the two terms is considered.

$$47.527 P_T R >> K_1 bc$$

Thus,

$$W \approx [47.527 P_T R]^{2/3}$$
 (2.14)

To determine how accurate this simplification is, the equation is used to approximate the total weight of a number of helicopters for which the parameters are available. As Table 2.1 indicates, the weight approximation formula yields values within six percent of the actual total weight of these helicopters.

H. FIGURE OF MERIT

A figure of merit, FM, has been defined for the helicopter as the ratio of the ideal rotor induced power to the actual power required to hover, with non-uniform induced velocity, tip losses and profile drag power.

TABLE 2.1
HELICOPTER WEIGHT COMPARISON

HELICOPTER	TOTAL GROSS WEIGHT	CALCULATED GROSS WEIGHT	PERCENT OF ACTUAL
	(1000 lbs)	(1000 lbs)	GROSS WEIGHT
AH-64	14.66	14.69	101%
UH-1N	14.20	13.74	97%
н- зн	21.00	20.63	98%
S 76	10.00	9.90	99%
UH-6DA	20.25	19.33	95%
H-54B	42.00	42.00	100%
H-53D	42.00	41.00	98%
H-53E	73.50	69.00	84%

In a hover, the figure of merit may be written as:

$$FM = \frac{1}{\sqrt{2}} \cdot PL \cdot \frac{DL}{\sqrt{\rho}}$$

$$= \frac{CT^{1.5}}{\sqrt{2C_p}}$$
(2.15)

The figure of merit is customarilty plotted against the quantity CT/σ . According to Zalesch [Ref. 2], CT/σ , is proportional to the average blade angle of attack and can be used as a measure of rotor efficiency. The curve in Figure 2.1 is based on data from Reference 2 for a typical tail rotor helicopter.

Main Rotor Hover Performance

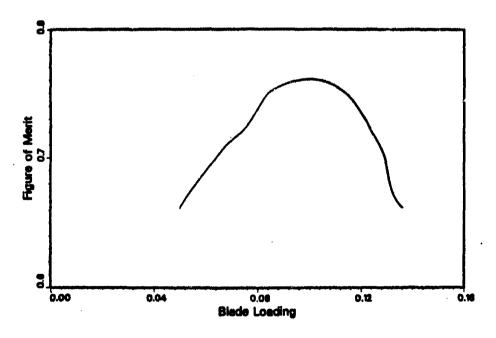


Figure 2.1. FM Versus Blade Loading CT/σ

Previous studies have shown that a figure of merit between 0.70 and 0.80 is considered average. [Ref. 3]

If the induced power is between 70 and 80 percent of the total power, the figure of merit will be approximately 0.75.

With the figure of merit limited to values between 0.70 and 0.80, the following simplification can be made, assuming the hover condition of thrust equaling weight and standard sea level conditions:

$$FM = \frac{W^{3/2}}{67.214 P_T R}$$
 (2.16)

For Navy helicopter design, the rotor radius has been limited by flight deck spotting constraints to less than 30 feet; the exception to this is the H-3, R = 31 feet and the H-53, R = 36 to 38 feet [depending on the model]. However, these two helicopters work almost exclusively from large air dedicated ships such as the LPH, LHA and CV.

If the small deck operating assumption is made, equation (2.16) can be further simplified to [assuming R = 28 feet]:

$$P = \frac{W^{3/2}}{1881.98 \text{ FM}} \tag{2.17}$$

An FM of 0.80 will yield a P to W relationship of:

$$P_{T} = \frac{W^{3/2}}{1505.58} \tag{2.18}$$

while an M of 0.70 yields a relationship

$$P = \frac{W^{3/2}}{1317.39} \tag{2.19}$$

If equation (2.17) is solved utilizing the approximate weight relationship developed earlier of

$$W^{3/2} = 47.527 P_T R (2.14)$$

a value for the figure of merit of 0.707 is obtained. This is within the historical range of values.

I. TAIL ROTOR SIZING

A historical analysis of typical helicopters [Ref. 3), shows the following empirical relationship for the tail rotor radius

$$R_{\rm T} \simeq 1.3 \left[\frac{\rm GW}{1000}\right]^{1/2} [ft]$$
 (2.20)

when comparing the results of this equation with actual tail rotor radius data, it was found that if a multiplication factor of 1.2 is used vice 1.3 a better approximation is obtained. The results are tabulated in Table 2.2.

J. FORWARD FLIGHT POWER CONSIDERATIONS

The total power in forward flight consists of induced, profile and parasite power. If the helicopter is a single rotor vehicle, the tail rotor power should be taken into

TABLE 2.2
TAIL ROTOR SIZING

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HELICOPTER	ACTUAL TAIL ROTOR RADIUS [FT]	APPROXIMA [2.20]	TION [FT] [2.21]
AH - 64	4.6	4.98	4.59
UH-1N	4.3	4.90	4.52
SH-3H	5.3	5.95	5.5
S-76	4.0	4.11	3.79
UH-60A	5.5	5.85	5.4
CH - 53D	8.0	8.42	7.78
CH - 53E	10.0	11.15	10.29

account, as well as all mechanical losses [transmission, etc.] for accurate calculations. However, a reasonable approximation can be obtained by considering only the main rotor and increasing this power figure by several percent to account for these losses.

Figure 2.2 is a plot of the induced, profile, parasite and total power curves for typical tail rotor helicopter.

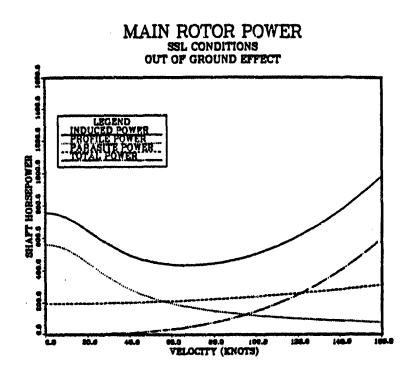


Figure 2.2. Power Required Versus Forward Velocity

The induced power drops off rapidly with increasing forward-velocity, whereas the parasite power increases rapidly.

Parasite power is the power required to overcome the drag forces created by the aircraft's geometry. These drag forces are due to pressure drag and skin friction.

Parasite drag is extremely sensitive to the helicopter's loading. It is generally a minimum for forward flight and increases for sideways flight. Helicopters are generally streamlined for forward flight and the flat plate area is a minimum in this direction. The equation for the parasite power is:

$$P_p = \frac{1}{2} \rho V_f^3 f_f$$
 (2.21)

The parasite power is a function of the cube of the forward velocity. As such, with the advent of high speed helicopters a great deal of consideration has been placed on streamlining the geometric shape in order to reduce this power requirement.

Blade element theory is commonly used to develop the profile power equation for forward flight. An excellent development of this equation is given in Reference 1.

The profile power equation in forward flight is:

$$P_{of} = \frac{1}{8} \sigma C_{do} \rho A V_T^3 [1 + 4.3 \mu^2]$$
 (2.22)

Equation (2.23) is a function primarily of the main rotor geometry. The variable with the most significance is the rotor tip velocity; increasing the tip velocity from 600 to 700 fps results in a 58.8 percent increase in profile power [assuming other factors are constant].

The induced power is a function of the induced velocity. In a hover, the total flow through the rotor system is induced. As the forward velocity increases, the mass flow rate through the rotor disc increases due to the forward translation of the helicopter. This reduces the induced velocity.

The equation for the induced power requirements at all forward velocities is:

$$P = T \cdot V_{it}$$
 (2.23)

where

$$V_{it} = \left\{ -\frac{V_f^2/V^2}{2} + \sqrt{\left[V_f^2/2V^2\right]^2 + 1} \right\}^{1/2} . V$$
 (2.23a)

At high forward velocities, the induced power required can be approximated as:

$$P_{i} = WV_{it} - \frac{W^{2}}{2\rho AV_{f}}$$
 (2.24)

The total power for forward flight is the sum of the induced, profile and parasite powers.

$$P_{T} = P_{i} + P_{o} + P_{p}$$
 (2.25)

$$P_{T} = T.V_{it} + \frac{1}{8} \sigma C_{do} \rho A V_{T}^{3} [1 + 4.3 \mu^{2}]$$

$$+ \frac{1}{2} \rho f_{f} V_{f}^{3}$$
(2.25a)

At high forward velocities, equation (2.23) can be substituted into equation (2.25), resulting in:

$$P_{T} = \frac{W^{2}}{2\rho AV_{f}} + \frac{1}{8} \sigma C_{do} \rho A V_{T}^{3} [1 + 4.3 \frac{V_{f}}{\Omega R}]$$

$$+ \frac{1}{2} \rho f_{f} V_{f}^{3}$$
(2.26)

If one makes the following assumptions:

$$W = const$$
 $C_{do} = const$

$$\rho = const$$
 $\sigma = const$

$$VT = const$$

Equation (2.26) reduces to

$$P_{T} = \frac{K_{1}}{R^{2}} + K^{2} R^{2} + P_{p}$$
 (2.27)

The derivative of equation (2.27) with respect to radius is:

$$\frac{dP_{T}}{dR} = -\frac{2K_{1}}{R^{3}} + 2K_{2}R \qquad (2.28)$$

Setting this equal to zero, one obtains:

$$-\frac{2K_1}{R^3} + 2 K_2 R = 0 (2.28a)$$

$$\frac{R}{2} * \left[-\frac{2K_1}{R^3} + 2 K_2 R \right] = 0$$
 (2.28b)

$$\frac{K_1}{R^2} = K_2 R^2 \tag{2.28c}$$

$$P_{i} = P_{o} \qquad (2.28d)$$

This defines point of minimum total power required for VMAX range. This corroborates with the results obtained by Waldo Carmona [Ref. 4].

If the total power required is differentiated with respect to forward velocity and is set equal to zero, it can be seen that

$$P_i = 3 P_0$$
 (2.29)

or

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$$\frac{W^2}{2\rho AV_f} = \frac{3\rho f V_f^2}{2}$$
 (2.30)

Solving this equation for velocity results in:

$$V_{f} = \left[\left(\frac{W}{A} \frac{A}{3f_{f}} \right)^{1/2} \right]^{1/2}$$
 ft/sec (2.31)

According to Carmona [Ref. 4], this corresponds to the best endurance velocity.

K. DENSITY EFFECTS ON TOTAL POWER

The effect of density on the total power required in forward flight is as follows:

The general operating altitudes of a helicopter are below 10,000 feet. The corresponding ICAO STANDARD ATMOSPHERE range for density is

$$\rho = 0.0023769 [1b sec^2/ft^4] SSL$$

$$\rho = 0.0017553$$
 [lb sec²/ft⁴] at 10,000 feet

 ρ/ρ SSL varies from 1 to .7385.

The effect on the components of P_{T} are as follows: Induced Power:

$$1/\rho/\rho SSL => 1 \text{ to } \frac{1}{.7385}$$

This translates to a 35 percent increase in the induced power.

Parasite and Profile Power:

Both parasite and profile powers are directly proportional to the density ratio. Therefore, as you go up in altitude both $P_{\rm o}$ and $P_{\rm p}$ are reduced.

III. CARPET PLOT DESIGN STUDY

A. DESCRIPTION OF PROBLEM

Preliminary helicopter design involves one with a wide range of choices. For any given payload and performance specifications, there a number of helicopter designs that satisfy the requirements. The problem in the preliminary design process is narrowing these possibilities and selecting the design which will provide the best helicopter for the mission.

Obviously, the operating environmental constraints help to define the basic configuration. These constraints are usually specified in the Request for Proposal [RFP], in the case of a military helicopter. For example, typical constraints placed on the design of a Navy helicopter are the size of the ship deck and hangar from which it will be operating, the requirement for a blade fold system, dual engine configuration and IFR capability.

Even with these design constraints, there is still a great deal of leeway. In order to insure that the best helicopter design is selected, an appropriate number of solutions satisfying the specifications should be investigated. Since each solution is generally characterized by a different combination of design parameters, the

selection, according to Greenfield [Ref. 5], can best be made through a parametric study which allows for the optimization of many design parameters.

One method of parametric analysis used is Carpet Plots. This method is based on the simultaneous graphical solution of the weight and hover performance equations. To this solution set is added to the environmental constraints to the helicopters size. This effectively brackets the area of acceptable design solutions.

This method assumes that minimum gross weight is the criterion by which the best [or optimum] design parameters are selected.

B. ASSUMPTIONS

- 1. Airfoil used is a derivative of the NACA 0012 with the following mean approximate values from Reference 5.
 - a = slope of airfoil section lift curve, $dC_t/d\alpha$, per rad.
 - a = 5.73
 - δ = blade section drag coefficient
 - $\delta_0 = .009$
 - $\delta_2 = .3$
- 2. a) The tail rotor radius is assumed to be .16 times the main rotor radius [Ref. 5].

- b) The distance between the rotors, or tail rotor moment arm, ℓ_{TR} is 1.19R [Ref. 5]. These ratios reflect the values of maximum rotor diameter and overall length specified as size limitations.
 - 3. B = .97. Historical approximation [Ref. 7].

C. METHODOLOGY

In order to properly develop the weight and performance equations required for a carpet plot design study, the payload and performance specifications of the helicopter are needed. This data is used to tailor the equations for the design.

The equations will be developed here for a four-place light helicopter. The equation development procedure is applicable to other size helicopters; the development for a medium helicopter, 20,000 lb weight class, is to be found in Appendix B.

The following specification requirements which are similar to those in Reference 5 will apply to this design:

- 1. The rotor diameter should be less than 35.2 feet.
- 2. The overall length should be less than 41.4 feet.
- 3. The gross weight of the helicopter should not exceed 2,450 lbs.
- 4. The helicopter should be capable of hovering, out of ground effect at 6,000 feet with an ambient air temperature of $95^{\circ}F$.

- 5. The useful load at hover shall consist of, as a minimum, 200 lbs for the pilot, 400 lbs of payload and sufficient fuel to give the helicopter up to three hours endurance at sea level conditions.
- 6. Maximum speed of at least 110 knots using Normal Rated Power, at sea level.
- 7. Total Power Required at 6,000 feet and 95°F shall be not more than 206.

D. HOVER EQUATIONS

1. The main rotor power required to hover out of ground effect is

Total Main Rotor Power [Hover] = Rotor Profile Power + Rotor Induced Power

$$P_{T} = \frac{1.13W}{550B\sqrt{2\rho_{o}}} \sqrt{\frac{DL}{\rho/\rho_{o}}}$$

$$+ \frac{6WV_{T}}{4400} \frac{\rho/\rho_{o}}{C_{LRo}} \left[\delta_{0} + \delta_{2} \left[\frac{C_{LRo}}{\alpha\rho/\rho_{o}}\right]^{2}\right]$$
(3.1)

At an altitude of 6,000 feet and a temperature of 95° , ρ/ρ_{\circ} = .749395. Therefore, equation (1) can be simplified to:

$$P_{T6000/95}^{\circ}_{f} = .035479W[DL]^{1/2} + \frac{.91971}{C_{LRo}} [10]^{-5} (1 + 1.80779 C_{LRo}^{2})W V_{T}$$
 (3.2)

The tail rotor thrust required to counterbalance the main rotor torque is:

$$T_{TR} = \frac{550 P_{T}R}{\ell_{TR} V_{T}} = \frac{550 P_{T}}{1.19 V_{T}}$$
 (3.3)

where ℓ_{TR} has been defined as 1.19R. With R_{TR} defined as .16R, the tail rotor disk loading can be written, using equation (3) as:

$$DL_{TR} = \frac{T_{TR}}{A_{TR}} = \frac{550 P_{T}}{1.19 V_{T}} \frac{1}{\pi (.16R)^{2}}$$

$$= \frac{550 P_{T}}{1.19 (.0256) V_{T}} \frac{DL}{W}$$
(3.4)

Greenfield [Ref. 5], in his development, assumes that the tail rotor tip speed is equal to the main rotor tip speed and that δ_{TR} = .02 and β_{TR} = .90. With these assumptions the equation for the tail rotor power required to hover can be written as:

$$P_{T_{TR}_{Hover}} = 2055.7 \left[\frac{DL}{W \rho/\rho_{o}} \right]^{1/2} \left[\frac{P_{T_{Hover}}}{V_{T}} \right]^{3/2} + \frac{.012605 P_{T_{Hover}}}{C_{LRTR}}$$

$$(3.5)$$

The equation for the tail rotor mean blade lift coefficient can be written as

$$C_{LRTR} = \frac{P_T}{562.5(\rho/\rho_0)}$$
 (3.6)

if it is assumed that the tail rotor is designed to counterbalance a sea level main rotor torque equivalent to 90 percent of the installed power.

Substituting equation (3.6) into equation (3.5) one obtains the following expression for hover tail rotor power:

$$P_{T_{TR6000/950}} = 2374.7 \left[\frac{DL}{W} \right]^{1/2} \left[\frac{P_{T_H}}{V_T} \right]^{3/2} + 5.3134$$
 (3.7)

It is assumed that the gear losses amount to 3 percent and that there is a 1 percent cooling power loss, the total brake horsepower required to hover becomes:

$$P_{T} = \frac{P_{Tm} + P_{TTR}}{96}$$
 (3.8)

Empirical studies have shown that the tail rotor power required to hover can be approximated by

$$P_{TAC} \sim$$
 .8 [total horsepower to hover]

This allows one to write the main rotor power required to hover as:

$$P_{Tm} = (.88)(P_{Tm})$$
 (3.9)

Following Greenfield's [Ref. 5] development further, if equations (3.2) and (3.7) are substituted in equation (3.8), one obtains

$$P_{T_{H6000/95}^{\circ}} = .036757 \text{ W } \sqrt{DL}$$

$$+ \frac{.95803}{C_{LRo}} (10)^{-5} [1 + 1.80779 C_{LRo}^{\circ}] \text{ W } V_{T} (3.10)$$

$$+ 2473.6 \sqrt{\frac{DL}{W}} \left[\frac{P_{Tm}}{V_{T}}\right]^{3/2} + 5.5348$$

Utilizing the approximation for tail rotor power, equation (3.9), equation (3.10) can be solved for W (gross weight) as a function of variables V_{T} (tip speed), DL (rotor disk loading), C_{LRO} (rotor mean lift coefficient) and P_{T_H} (total power to hover).

$$W = \frac{K_1 \left[1 - 411.51 \frac{DL^{3/4}}{V_T^{3/2}} \left(1 + K_2 \frac{V_T}{\sqrt{DL}} \right)^{1/2} \right] - K_3}{V_T + K_4 \sqrt{DL}}$$
(3.11)

where:

$$K_1 = P_{T6000/90} \circ \frac{(10)^5}{K_5}$$
 (3.11a)

$$K_2 = \frac{.00025929}{C_{LRO}} (1 + 1.80779 C_{LRO}^2)$$
 (3.11b)

$$K_3 = \frac{553480}{K_5} \tag{3.11c}$$

$$K_4 = \frac{3695.7}{K_5} \tag{3.11d}$$

$$K_5 = \frac{.95803}{C_{LRo}} (1 + 1.80779 C_{LRo}^2)$$
 (3.11e)

Equation (3.11) has been programmed in Appendix B and solved for tip speeds from 600 to 700 cps and $C_{\mbox{LR}}$ of .3 to .7.

Equation (3.11) is one of the two primary equations used to obtain the data required for a carpet plot design analysis. Generally, the variables $V_{\rm T}$, DL, $C_{\rm LRo}$ and $P_{\rm T}$, that are required for solution have specific ranges of values, depending on the weight class of the helicopter being designed. The graphical results of equation (3.11) for tip speeds of 600 to 700 fps and mean lift coefficients between .3 and .7 are illustrated in Figure 3.1.

Both the Fortran and Disspla programs, as well as a decision making flow chart are provided in Appendix C to aid in using this method for a design solution.

E. WEIGHT EQUATIONS

Weight equations need to be developed that realistically reflect the sizing class of the helicopter being designed.

The evolution is greatly simplified if a specific engine

Weight Equation Plot: CLR=0.5 Weight Equation Plot: CLR=

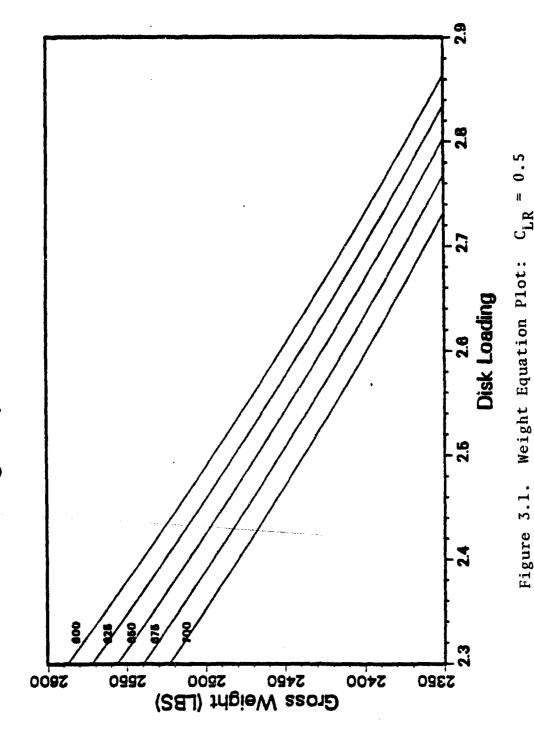


Figure 3.1.

installation [# and horsepower] is assumed, since the weight of a number of components depend only on the installed power; this would include such terms as the engine controls and accessories. Another category would be those components whose weights depend on either the gross weight on two or more of the following in combination: rotor tip speed (V_T) , rotor diameter (R), rotor solidity (σ) .

The equations developed here are taken from the Hiller Aircraft Corporation Performance Data Report. [Ref. 5] In this report they assumed a specific engine installation, the Allison T-63 with a military power rating at sea level of 250 horsepower.

There is a possible problem of the validity of these weight relationships when applied to different helicopter design categories. However, assuming a specific engine determines a number of the component weights, and thus minimizes the inaccuracies. Using the weight estimation relationships developed in the Helicopter Design Manual [Ref. 2], the engine, control and accessory weight can be calculated and the weight formulas developed here applied to give a representative useful load and empty weight formula for preliminary design analysis. This is done in Appendix C, for a 20,000 pound class helicopter.

The following relations are used to reduce the component weight formulas for the specification helicopter:

$$W/DL = A = \pi R^2$$
 (3.12)

$$W/PL = MHP = 250$$
 (3.13)

(Military rating for Allison T-63 at sea level.) (PL = Power Loading.)

$$P = \sqrt{A/V_T}$$
 (3.14)

Using these equations the component weight for the specified helicopter empty weight may be reduced to the following:

Engine, Controls and Accessories = 617.5 lbs.

Engine Section Group
$$.053[W/PL]^{1.07} = 19.5 \text{ lbs. } (3.15)$$

Main Trans-
mission
$$10.43 \frac{V^{1.295}}{(PL V_T)^{.863}} = 1221 p^{.803}$$
 (3.16)

Rotor Drive Shaft 5.56
$$\frac{W^{1.05}}{(PL V_T)^{.7}(DL)^{.35}} = 266 p^{.7}$$
 (3.17)

Tail Rotor 32.22
$$\frac{W^{1.14}}{(PL V_T)^{1.7}} = \frac{17449}{V_T^{1.14}}$$
 (3.18)

The engine, controls and accessories category includes such items as lubrication and oil cooling system, engines, communications, engine controls, engine accessories, instruments starting system, furnishing, flight controls, electrical system and stabilization. These are considered fixed weight items determined from specification of the engine and weight class of the helicopter.

Tail Rotor Gear Box 3.7
$$\frac{W.75}{(PL V_T.5(DL).25} = 59.47 \sqrt{P}$$
 (3.19)

Tail Rotor
Drive .124
$$\frac{W^{1.355}}{(PL V_T)^{.57}(DL)^{.785}} = 2.886 P^{.57} \sqrt{A}$$
 (3.20)

Rotor Blade 35.15
$$\frac{W^{1.185}_{\sigma}.33}{V_{T}(DL).185} = 35.15 \frac{W}{V_{T}} A.^{185}_{\sigma}.^{33}$$
 (3.21)

Rotor Blade Artic- 19.77
$$\frac{W^{1.205}_{\sigma}.33}{V_{T}(DL).205} = 19.77 \frac{W}{V_{T}} A.^{205}_{\sigma}.33$$
 (3.22)

Rotor Hub
Teetering .0088
$$\frac{\text{W}^{1.21}}{\text{DL}^{.21}} = .0088 \text{ WA}^{.21}$$
 (3.23)

Rotor Hub
Artic- .00975
$$\frac{\text{W}^{1.21}}{\text{DL} \cdot 21} = 00975 \text{ WA} \cdot 21$$
 (3.24)

Fuel System .416 per gallon capacity = .0615 W_F (3.25) where W_F = fuel weight.

The individual component weights may now be combined into a single expression for the helicopter empty weight.

$$W_{e} = 617.5 + .0617W_{F} = 1221P^{.863} + 266P^{.7} + \frac{17449}{V_{T}^{1.14}}$$

$$+ 58.47\sqrt{P} + 2.886P^{.57}\sqrt{A} + .191W^{.916} + .0294W^{.99}$$

+ appropriate rotor blade and hub weights.

As stated earlier, the design specifications called for a useful load consisting of a pilot (200 lbs), payload (400 lbs) and the required fuel weight ($W_{\rm F}$). The fuel weight is calculated for the Allison T-63 in the following manner: endurance of three hours at 85 percent of normal rated powered for the T-63 is 180.2 HP and the specific fuel consumption at this power is .783 lbs fuel/BHP HR. Including an allowance for a three-minute warm-up at NRP and using a 5 percent correction factor on SFC, as specified in Reference 5, the fuel weight becomes:

$$W_F = 3(180.2)(.822) + \frac{3}{60}(212)(777)$$
 (3.27)

An allowance should also be made for oil plus trapped fuel. This is estimated at 20 lbs.

The total useful load is the sum of the useful load items.

$$W_{11} = 200 + 400 \div 452.6 + 20 = 1072.6 \text{ lbs}$$
 (3.28)

A new variable, $W_{\rm BAR}$, is defined as the sum of the emply weight plus useful load. It is the of equations (3.26) and (3.28).

$$W_{BAR} = 1717.9 + 1221P^{.863} = 266F^{.7} + \frac{17449}{V_{T}^{1.14}} + 58.47\sqrt{P}$$

$$+ 2.886P^{.57}\sqrt{A} + .191W^{.916} + .0294W^{.99}$$
(3.29)

+ appropriate rotor blade and hub weights.

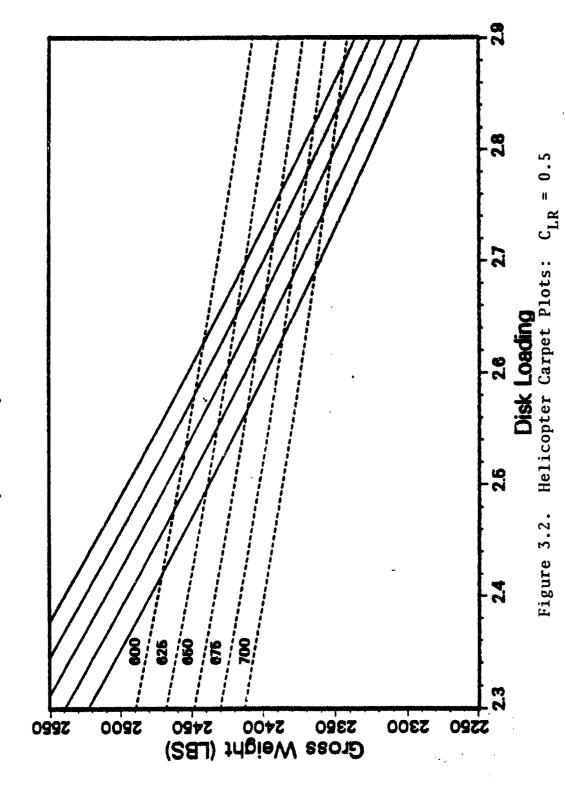
Equation (3.11) together with equation (3.29) form the basis of a carpet plot design study. These equations are solved simultaneously for $W_{\rm BAR}$. This solution is best illustrated graphically, as in Figure 3.2. The graph in Figure 3.2 was generated for a specific value of $C_{\rm LR}$ over a range of tip speeds [600 to 700].

F. GRAPHICAL ANALYSIS

Graphs similar to Figure 3.1 are generated for several value of $\ensuremath{C_{LR}}$, and are then cross plotted to form Figure 3.2.

The mean lift coefficient, $C_{\mbox{LR}}$, values are selected based on what is considered the historical average range of

Helicopter Carpet Plots: CLR=0.5



values. Figure 3.3 is basic plot for a carpet plot design study. Programs are provided in Appendix D which will generate the required data sets and plots of Figures 3.2 and 3.3.

The solution field depicted in Figure 3.3 is too large to be of great analytic value and as such must be reduced. Three parameters, maximum gross weight, rotor diameter (both specified in the Design Specification) and the aspect ratio can be used to narrow the field of solutions.

1. Rotor Diameter Boundary

A net to exceed value for the rotor diameter is generally given in the design specifications. This limiting value is based on the operating environment of the helicopter. With R max specified, there is a linear relationship between the disk loading and the gross weight.

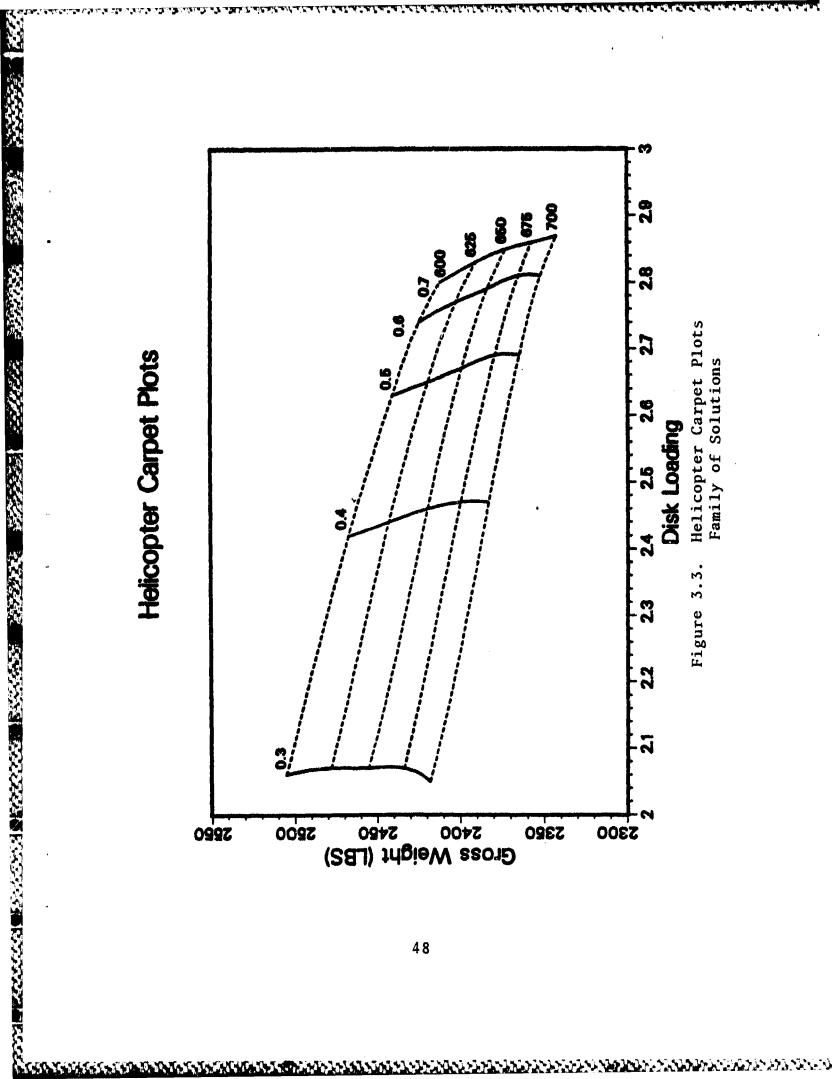
$$DL = \frac{W}{A} = \frac{W}{\pi R^2}$$

The resulting bracketing of the solution field by applying both the maximum gross weight and maximum rotor diameter limits to the carpet plot are shown in Figure 3.4.

2. Respect Ratio Boundary

It is evident that a further restriction is still necessary to completely define the region of acceptable





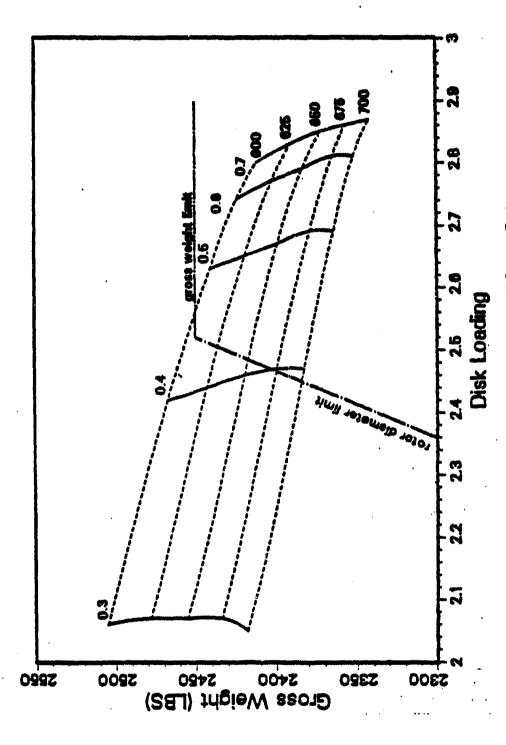


Figure 3.4. Helicopter Carpet Plots Rotor Diameter and Weight Limits

design solutions. Studies have indicated that a main rotor aspect ratio of 21, 1 is a representative upper limit. Thus

$$21 \ge \frac{R < mr}{C < mr} = \frac{b}{\pi \sigma} = \frac{b \circ_{O} C_{LR} V_{T}^{2}}{\sigma \pi DL}$$

or

$$DL \geq \frac{b \rho C_{LR} V_T^2}{126\pi}$$

For the case of a two bladed main rotor equation (3.30) reduces to:

DL
$$\geq$$
 .000012 $C_{LR} V_T^2$

The detemination of this boundary graphically is as follows:

The hover solution plot of Figure 3.2 is replotted 2 relative to the coordinates disk loading and design mean blade lift coefficient. The limiting curves for DL = .000012 $C_{LR} V_T^2$ are then plotted. The intersection with the appropriate constant tip speed lines of the hover solution represent the aspect ratio boundary; Figure 3.5.

¹For a helicopter rotor, the aspect ratio is defined as the radius divided by the chord.

²For clarity lines of constant gross weight are omitted.



Application of the second of t

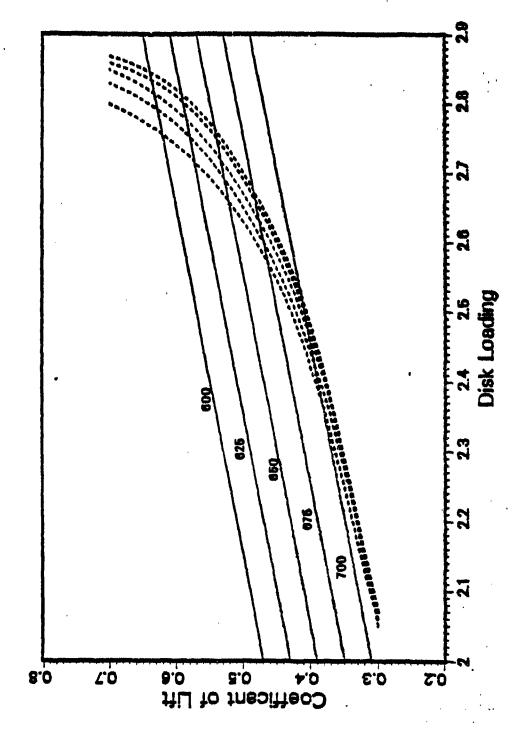
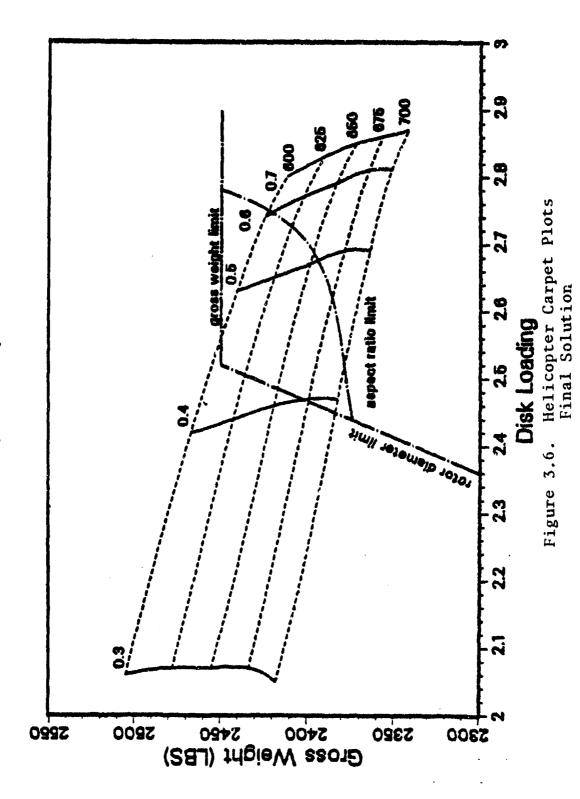


Figure 3.5. Aspect Ratio Boundary Plot

These intersection points are then cross plotted onto Figure 3.4. Figure 3.6 represents a graphical plot of the solution set satisfying the performance and structural design criteria of a small observation helicopter as specified in this study.

Michight Mercess secress serving markey

Helicopter Carpet Plots



IV. HESCOMP

A. DESCRIPTION OF PROGRAM

HESCOMP is a helicopter sizing and performance computer program developed by the Boeing Vertol Company. The program was originally formulated to provide for rapid configuration design studies.

A number of programming options are available to the user of HESCOMP. When the type and mission profile of the helicopter are known, HESCOMP may be used to size the aircraft. Alternately, it may be used for mission profile calculations when the sizing details [gross weight, payload, engine size, etc.] are specified. A combination of these two options is also available; the program may be used to first size a helicopter for a primary mission and then calculate the off-design performance for other missions. Finally, HESCOMP may be used solely for obtaining helicopter weight.

Sensitivity studies involving both design and performance tradeoffs can easily be done with HESCOMP. Incremental multiplicative and additive factors can be imbedded in the input data.

The various helicopter configurations that may be studied using HESCOMP are detailed in Table 4.1.

TABLE 4.1

HELICOPTER CONFIGURATIONS WHICH MAY BE STUDIED USING HESCOMP

HELICOPTER CON			1	1		
Additional Lift/Propulation System Components Which Must be Added to "Pure"		Propolier for Nuxiliery	Auxiliary	Type of Auxiliary Independent Engines		
Type (Both Single & Tandem Rotor) Conf.		Propulsion	Independent Engines	T/Sheft	T/FAD	T/Jo
Pure Helicopter						
Winged Helicopter	×					
Compound Helicopter		•				1
 Coupled (prim. engines drive auxiliary propulsion systum) 	×	X				
(2) Auxiliary independent propulsion system		•				
(a) T/Shaft engine (b) T/Fan engine (c) T/Jet engine	X X	ж.	X X X	. *	×	×
Auxiliary Propulsion Helicopter			,			
(1) Coupled (prim. engines drive suxiliary propulsion system)		X				
(2) Auxiliary Independent propulsion system					e/**	
(a) T/Shaft engine (b) T/Fan engine (c) T/Jet engine		×	X X	X	×	
oamim1 Motor Helicopter				, ,		
(1) Coupled (prim. engines drive suxiliary propulsion system)		x				
(2) Auxiliery Independent propulation system						
(a) T/Shaft ongine (b) T/Fan ongine		'π	x x	ж.	x	
(c) T/Jat engine			, x			x

B. PROGRAM MODIFICATIONS AND IMPLEMENTATION

The computer program received from Boeing Vertol required some modification and reformating in order to run properly on the Naval Postgraduate School IBM system.

These alterations did not, however, alter the program output or usability.

HESCOMP, as received from Boeing Vertol, was 17821 lines long and set-up as a sequential data set to be assemble on a 'G compiler'. The Batch processing system at the Naval Postgraduate School accepts only programs set to run on 'H compiler'. Normally, the differences between these two compilers are minor and programs that run on one will run on the other. However, this was not the case with HESCOMP.

In order to facilitate the program debugging process, HESCOMP was reformatted as a partitioned data set. What this effectively did was to break the program down into eight members of approximately 2000 lines. The program breakdown is illustrated in Table 4.2.

Each of these were compiled individually and then error codes analyzed. The member data set was then modified as required to properly compile.

Once all the members of the partitioned data set compiled properly, HESCOMP was again formated as a sequential data set and run utilizing input data for which there was a known output. This insured that the modifications made to the original program had not altered the logic, ie., gave faulty results.

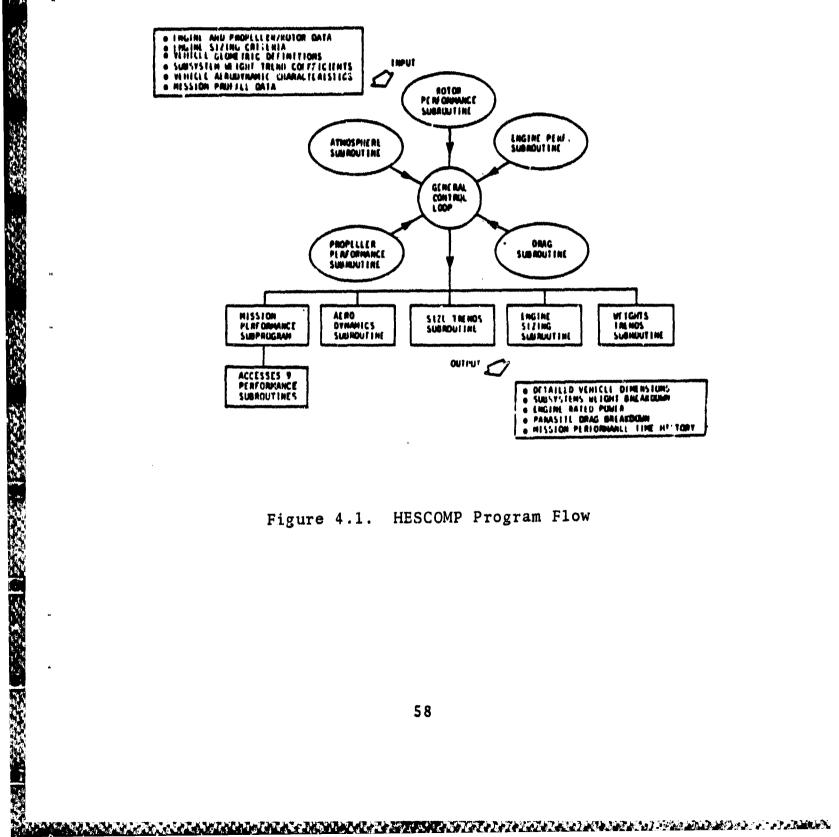
The control language program to access HESCOMB on the Batch processing system and a sample input and out data set are shown in Appendix D. These are also available on the Aero disk for copying and use.

TABLE 4.2
PARTITIONED DATA SET

MEMBER	NAME LINE	N	UMBER	SIZE	FIRST	ROUTINE
S1	1	-	1681	1681	AE	RO
S2	1682	-	4132	2451	CL	IMB
S3	4133	-	6531	2399	XI	BIV
S4	6532	-	8974	2443	PO	WAVL
S 5	8975	-	10870	1896	PR	INT 1
S 6	10871	-	13042	2172	P.O	T POW
S7	13043	-	15383	2341	CR	US 3
S8	15384	-	17821	2448	TA	XI

C. PROGRAM FLOW

The program is conceptually outlined in Figure 4.1, [Ref. 7]. The program flow is monitored by a general loop, which controls a series of peripheral programs. There are



A. 18.50

a total of 44 subroutines. Detailed program descriptions cam be found in Section 4 of the HESCOMP User's Manual.

D. PROGRAM INPUT

Program input can be loosely group into ten categories: general information, aircraft descriptive information, mission profile information, rotor tip speed schedule, incremental rotor performance, auxiliary propulsion input schedule, engine cycle information, rotor performance information, propeller performance information, and supplementary input information.

The actual amount of input data requires varies greatly with the program options selected. An example of a data set formatted to run on the IBM system is shown in Appendix E. A more detailed explantion is available in Section 5 of the HESCOMP User's Manual.

E. PROGRAM OUTPUT

An example of the program output is included in Appendix E. The printout consists of general data, input data, sizing data [program output] and mission performance data [for the size helicopter]. Detailed descriptions of these and diagnostic error statements are described in Section 6 of Reference 6.

V. CONCLUSIONS AND RECOMMENDATIONS

Three approaches to analyzing a preliminary helicopter design were explored in the course of this paper. It was found that a number of the performance equations could be greatly simplified with little degradation in the final results. A sensitivity analysis brought further insight into the inter-play of the parameters and how changes in them tended to effect the helicopter performance equations.

Carpet Plots provided the most interesting method of analysis. Development of a graphical solution matrix using this method provides a usual interpretation of what is occurring when key parameters are varied.

Two cases were explored; a light observation helicopter in the 3,000 pound weight class and a heavier utility helicopter in the 20,000 pound weight class. The Carpet Plot method provided reasonable solutions in both cases. In doing the analysis for the utility helicopter, the initial weight estimation equation had to be adjusted upward by approximately 2,000 pounds for the equations to intersect properly. This is not considered a limitation to this method of analysis, however, it does point up an area for further investigation. It may be possible to develop more accurate weighing factors for this equation when dealing with higher gross weight helicopters.

HESCOMP provides a plethora of information to the user. However, the price is the amount of inputed data required for even a simplified analysis. At a preliminary design level of analysis, the other methods explored provide a quicker first-cut look at the potential design.

APPENDIX A: NOMENCLATURE

TERM	DEFINITION	UNITS
a	Slope of Airfoil Section Lift Curve	Radians
A	Rotor Disk Area	ft ²
AR	Aspect Ratio	Dimensionless
A _{TR}	Tail Rotor Disk Area	ft ²
b	Number of Rotor Baldes	Dimensionless
В	Tip Loss Factor	Dimensionless
С	Main Rotor Cord	ft
C _{do}	Profile Drag Coefficient at Zero Lift	Dimensionless
CLRo	Design Mean Blade Lift Coefficient at Sea Level	Dimensionless
$^{C}\mathbf{_{T}}$	Coefficient of Thrust	Dimensionless
C _p	Coefficient of Power	Dimensionless
δ	Blade Section Drag Coefficient	Dimensionless
DL	Disk Loading	lb/ft ²
FM	Figure of Merit	Dimensionless
НР	Horsepower	
L _{TR}	Tail Rotor Moment Arm	ft
ρ	Air Density	$1b \sec^2/ft^4$
μ	Advance Ratio	Dimensionless
R	Rotor Radius	ft

TERM	DEFINITION	UNITS
$P_{\overline{T}}$	Total Power	НР
P _{TM}	Main Rotor Total Power	НР
P _{TTR}	Tail Rotor Total Power	Нр
Po	Profile Power	НР
P _i	Induced Power	HP
P _p	Parasite Power	HP
PL	Power Loading	LB/HP
R	Rotor Radius	ft
T	Thrust	НР
v _I .	Induced Velocity	.ft/sec
$v_{\mathbf{F}}$	Forward Velocity	ft/sec
v	Aircraft Forward Speed	ft/sec
v_T	Rotor Tip Speed	ft/sec
W	Aircraft Gross Weight	1bs
₩c	Empty Weight	1bs
W _F	Fuel Weight	1bs
Wu	Useful Load	1bs
WBAR	Empty Weight Plust Useful Load	1bs
σ	Solidity	Dimensionless

APPENDIX B: CARPET PLOT FORMULATION FOR 20,000 LB. CLASS HELICOPTER

B1 SPECIFICATIONS:

Maximum Gross Weight: 20,000 pounds Maximum Rotor Diameter: 30 feet

- B2 PRELIMINARY ENGINE SIZING:
 - B2.1 Utilize equation (2.14) to determine engine horsepower category.

 $W = [4.753P_TR]^{2/3}$

 $20,000 = [47.53P_T \ 30]^{2/3}$

 $P_T = 1983 HP$

- B2.2 Use the engine selection parameters tables B.1 to determine the number and type of power plant [table taken from Reference 3].
 - B2.2a Type and number selected: 2 type C.
 - B2.2b Specifications:

Dry Weight Per Engine: 423 pounds

Shaft Horsepower at Standard Sea Level:

Military 1561 HP

Normal 1318 HP

- B3 WEIGHT EQUATION FORMULATION
 - B3.1 To obtain the engine control and accessory weight use items 7, 9, 10, 11, 12 and 13 of the weight estimation relationships developed in Reference 3 for a utility helicopter:
 #7: 609 lbs; #9: 129 lbs; #10: 76 lbs;
 #11: 410 lbs; #12: 439 lbs; and #13: 302 lbs.

TABLE B.1

ENGINE SELECTION PARAMETERS

The following turboshat power plant data are presented for one engine.

Engines:	Α	В	C	D*	E	F
Dry Weight (1bs)	158	288	423	709	58 0	750
SHP (ssl) Militar Normal Cruise	y 420 370 278	708 639 494	1561 1318 1989	1800 1530 1148	2500 2200 1650	3400 3000 2250
SFC (ss1) Militar Normal Cruise	y .650 .651 .709	.573 .573 .599	.460 .470 .510	.595 .606 .661	.615 .622 .678	.543 .562 .610
Initial Costs	\$93K	\$100K	\$580K	\$360K	\$640K	\$700K
Operating Cost per hour/engine	\$8	\$16	\$2J	\$35	\$40	\$60
Preventative Main per hour/engine	t. \$25	\$50	\$100	\$125	\$160	\$220
MTBMA (hrs)	3.5	3.0	2.0	3.0	4.0	3.5
MDT (hrs)	0.7	0.6	0.5	1.3	2.0	2.6
MTBF (hrs)	185	210	205	285	280	320
MTBR (hrs)	600	750	800	800	1000	750

B3.2 Simplifications

$$\frac{W}{DL} - A = \pi R^2$$
 , $\frac{W}{2pm} = MHP = 31,00$; $P = \sqrt{\frac{A}{V_T}}$

B3.3 Engine Group

$$.053(5100)^{1.07} = 272 \text{ lbs}$$

B3.4 Main Transmission

10.43
$$\frac{W^{1.295}}{(\text{lpm V}_{t})} = 10.43 \frac{W^{.863} A^{+.432}}{(\text{lpm})^{.863} V_{T}^{.863}}$$

$$= (10.43)(3100).863$$
_P.863

B3.5 Rotor Drive Shaft

5.56
$$\frac{W^{1.05}}{(\text{lpm V}_T)^{7}} = 5.56(3100)^{7}P^{7}$$

$$= 1545P.7$$

B3.6 Tail Rotor

32.22
$$\frac{W^{1.14}}{(lpm V_T)^{1.14}} = \frac{307,600}{V_T^{1.14}}$$

B3.7 Tail Rotor Gear Box

3.7
$$\frac{W^{.75}}{(\text{lpm V}_T)^{.5} [\frac{W}{A}]} = (3.7)(3100)^{.5} p^{.5}$$

- = 206P.5
- B3.8 Tail Rotor Drive Shaft

.124
$$\frac{W^{1.355}}{(\text{lpm})} = (.124)(3100)^{.57} p^{.57} \sqrt{A}$$

- $= 12.12P.57 \sqrt{A}$
- B3.9 Landing Gear

AND THE PARTY OF THE PROPERTY OF THE PROPERTY OF THE PARTY OF THE PART

$$= .191W^{.916} + .0294W^{.99}$$

B3.10 Rotor Blades Articulated

19.77
$$\frac{W^{1.206}_{\sigma}.33}{V_{T}DL\cdot^{205}}$$

= 19.77
$$\frac{W}{V_T}$$
 A .205_{\sigma}.33

B3.11 Rotor Hub Articulated

.00975
$$\frac{W^{1.21}}{DL^{.21}} = .00975WA^{.21}$$

Calculation of fuel weight three hours at cruise SHP

1664 1bs

B3.13 Total Equation

WB = 12,987,* + 107948P.863 + 1545P.7
+
$$\frac{307600}{V_T^{1.14}}$$
 + 206P.5 + 12.12P.57 \sqrt{A}

$$+ .191W^{.916} + .0294W^{.99}$$

+ 19.77
$$\frac{W}{V_T}$$
 A.205 s.33 + .00975WA.21

B4 HOVER EQUATION

Following the formulation in Section of Chapter 3, the weight equation based on the design mean lift coefficient and power required is:

$$W = \frac{K_2 \left[1 - 411.51 \frac{DL^{3/4}}{V_T^{3/2}} \left(1 + K_3 \frac{V_T}{\sqrt{DL}} \right)^{1/2} \right] - K_4}{V_T + K_5 \sqrt{DL}}$$

This number was increased from 8987 to 12987 to bring the curves together. This reflects a 4000 lb useful load.

where:

$$K_{1} = \frac{.9583}{C_{LRo}} (1 + 1.8078 C_{LRo}^{2})$$

$$K_{2} = \frac{P_{T6000/950} (10^{5})}{K_{1}}$$

$$K_{3} = \frac{0.00025929}{C_{LRo}} (1 + 1.8078C_{LRo}^{2})$$

$$K_{4} = \frac{553480.0}{K_{1}}$$

$$K_{5} = \frac{3695.7}{K_{1}}$$

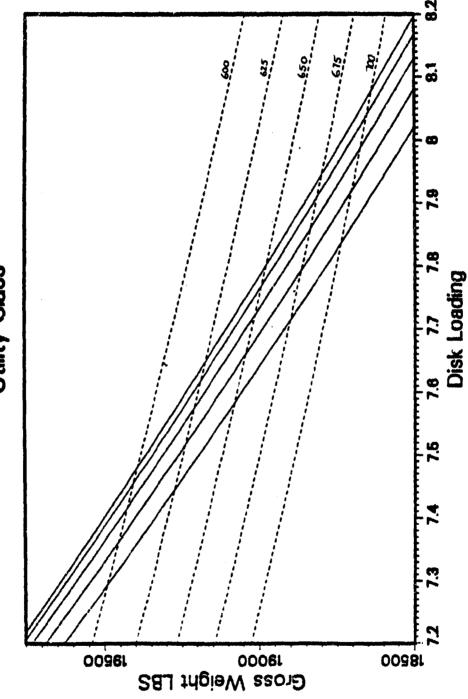
B.5 GRAPHICAL RESULTS

Figure B.1 is an example of equation (3.13) plotted against equation (B.4) for a specific design mean lift coefficient.

Figure B.2 illustrates the family of curves obtained when the design mean lift coefficient is varied from $0.3 \ \text{to} \ 0.7$.

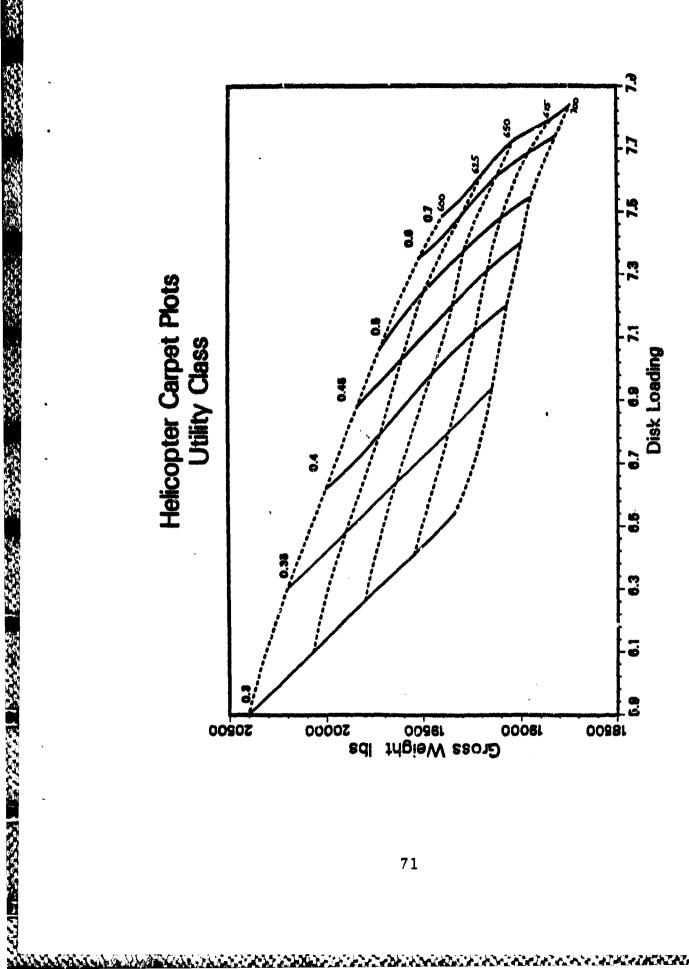
In Figure B.3 the solution matrix depicted in Figure B.2 is narrowed by the constraints placed on the gross weight, rotor diameter and aspect ratio.

Helicopter Carpet Plots: CLR=.70 Utility Class



Helicopter Carpet Plots: Utility Class

Figure B1.



Helicopter Carpet Plots Utility Class Figure B2.

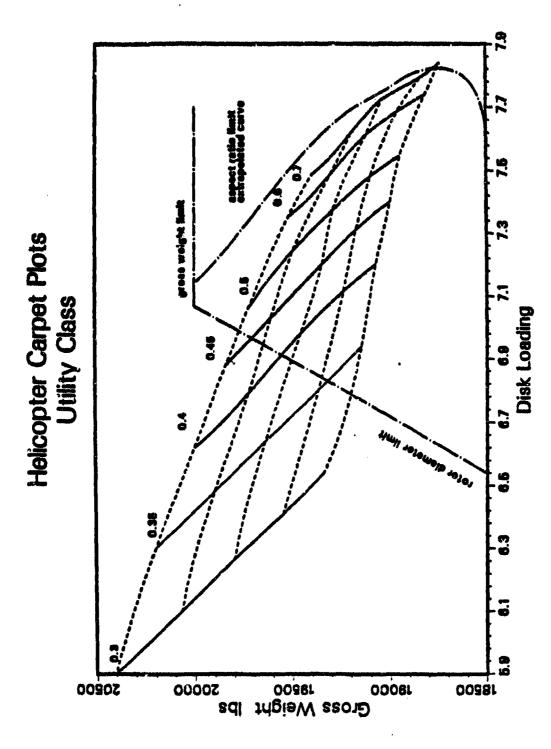
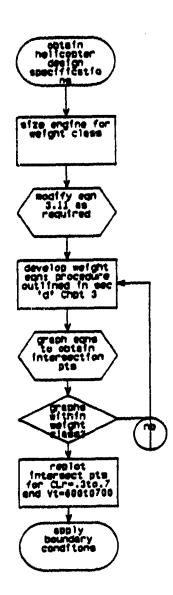


Figure B3. Helicopter Carpet Plots Utility Class

APPENDIX C. CARPET PLOT METHODOLOGY FLOW CHART AND EXAMPLE PROGRAMS:

This section contains a flow chart to help organize a carpet analysis and example IBM computer programs to produce the data sets and disspla graphs.



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LIGHT AS CALCULATED FFCM POWER EQUATION
USEFUL ICAD ILUS EMPTY WEIGHT
FCWER AVAILABLE IN HORSEPOWER
         PERL CIR, EL (150), W1 (150), W2 (150), W3 (150), W4 (150), W5 (150), W5 (150), W6 (15
              INTEGER I
-- DEFINE FILES -----
         CALL FRICHS ('FILEDEF ', '3
       CALL FRICHS ('FILECEF','4 ','DISK ','CRPT45',

BEAD DATA FROM FILE: CRPTX DATA A ------
              CC 10 I=1,99
CRFT1 DATA A
BEAD (3,70) DL (I), W1(I), W21(I), W2(I), W82(I)
CEPT2 DATA A
BEAD (4,71) W3(I), W23(I), W4(I), W84(I), W5(I), W85(I)
CONTINUE
                 CALL DISSFLA BCCTINES FOR PLOT -
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THIS PROGRAM IS DESIGNED TO ILLUSTRATE THE FAMILY CF SCIUTIONS FOR HOVER AND USEFUL LOADER FAMILY BEQUIES HEATS OF A TESTERING SOTOR SISTEM WITHOUT ANY BOUNDARY COMPETIONS CASSERVATION CLASS
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CL4 EQUALS THE DISK LOADING PCF CLR=.6

CL5 EQUALS THE LISK LOADING PCF CLR=.6

CL6 EQUALS THE LISK LOADING PCF CLR=.7

W3 EQUALS THE LISK LOADING FCF CLR=.7

W3 EQUALS THE BEIGHT FOR CLR=.3

W4 EQUALS THE BEIGHT FOR CLR=.7

W4 EQUALS THE BEIGHT FOR CLR=.7

W5 EQUALS THE BEIGHT FOR CLR=.7

W5 EQUALS THE BEIGHT FOR CLR=.7

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W7 EQUALS THE BEIGHT FOR CLR=.7

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W7 EQUALS WEIGHTS AT YT=6675

W7 EQUALS WEIGHTS AT YT=6675

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       CALL DISSELA REUTINES FOR PLOT

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CALL PAGE (12-0, 9-5)
CALL PAGE (12-0, 9-5)
CALL PHYSOR (1-0, 1-2)
CALL PHYSOR (1-0, 6-5)
CALL HEADD (10-0, 6-5)
CALL SAUSSL
CALL BASALF (*I/CSTC*)
CALL HIXALF (*SIANC*)
CALL HIXALF (*SIANC*)
CALL HIXALF (*SIANC*)
CALL HEGHT (-16)
CALL XNAME (*CLICK (1) OACINGS*, 100)
CALL HEGHT (-200)
CALL HEGHT (-200)
CALL HEGSET (*CLICK (1) OACINGS*, 100)
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GRAFHICAL EELICUPTER DESIGN PROGRAM
FAMILY OF SOLUTIONS
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EY AL HANSEN
                                                                                                                                                             THIS PECGRAM IS DESIGNAL TO ILLUSTRATE THE FAMILY CF SCIUTIONS FOR HOVEF AND USEFUL LOAD REQUIREMENTS OF A TESTERING FOTOR SYSTEM WITH FCTCR CIAMETER AND MAX GROSS BOUNDRIES.

CESEBVATION CLASS HELICOPTER
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                                                                             VARIABLES:
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USEFUL ICAD FLUS EMPTY WEIGHT
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LL5 EQUALS THE DISK IOADING FEGE CLR -- 7

LL5 EQUALS THE DISK IOADING FEGE CLR -- 7

LL7 EQUALS THE BESSET FOR CLR -- 7

LL7 EQUALS THE BESSET FOR CLR -- 7

LL7 EQUALS THE BESSET FOR CLR -- 7

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                                                                                                               THIS PROGRAM IS DESIGNED TO ILLUSTRATE THE PANILY OF SCIUTICENS FOR HOVEF AND ESEPTIAL TO THE PANILY REQUIREMENTS OF A TEREBRING ROTOR SYSTEM WITH SCIENT LIAMETER, EAX GROSS WEIGHT AND ASSECT RATIO ECUNDARIES.

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            ASSUMPTIONS: 1> ANGINESPECIPIED
            BEAL+4 CLE, PA, EI, K1, K2, K3, K4, K5, E, S, A, P, W(10), WB(10) INTEGER VI, D, I, CL
          CALL PRICES ('FILITEF','02
                                                                        . DISK
 Ç.
            CLB= DESIGN MEAN LIFT COEFFICIENT DC 90 CL=3.7 CLB=CL+(C.1) HEITE(2.10) CLB PA= POWER AVAILABLE HP PA=206 CL= DISK LOADING VI= TIP VELOCITY F1/SEC
 C
             CONSTANTS BASEC ON CIR
             R1=(0.9583)/CIR+(1+1.8078+CIR++2)

K2=PA+10++5/K1

K3=[0.00625929)/CIR+(1+1.8078+CIR++2)

K4=553486-0/K1

K5=5695-7/K1

DC 100 D=200,300

E1=D+(0.01)
              DO 110 VT=600,700,25
 Ç
                  WENT INCREMENTED
 ç
           ¥(I)=(K2+(1-(411.51+DL++.75)/(NT++1.5)+(1+K3+VT/DL++.5)=+.5)-K4)
1/(VT+K5+DL++.5)
            CALCULATION OF WE DATA
             A=6(I)/D1
B=(A/3,14)**-5
P#4**-5/Y3
S=(6.*DL)/(0.0023679*CLR*VT**2)
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110
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APPENDIX D. PROGRAMS TO ACCESS HESCOMP

This section contains the control language programs needed to access HESCOMP on the IBM main-frame computer.

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APPENDIX E: HESCOMP INPUT AND OUTPUT EXAMPLES

This section contains samples of the IBM computer input and output.

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SINGLE BOTCB
CCPF6UHD ABLICOPTER
AUX. INDEPENDENT 1/SHAFT CRUIISION

SIZE DATA 1815 200 CCNVERGED IN BITERATIONS

GEOSS BEIGHT = 17043.

FUSELACE

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MELICCOTES SIZING & PROPERS PROGRAM E-	PROFILE CAST LAG PACTOR COST LAG PACTOR	STRUCTURES GROUP A FEB	ENS. CONTROLS 350. 1 ENS. CONTROLS 240. 1 ENTROLS 240. 1 ENTROLS 30. 1 ENTROLS 24. 1 ENTROLS 75. CCNTFO 32. 1 ENTROLS 75. CCNTFO 32.
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FOTO B DATA

FOTO TAIL FCTOM SIZEE AT 1.650 FINES THE SOLIDITY
FEGURED TO SATISFY HOVERING TURN REQUIREMENTS AT 1.010 THP
THP THP TO SATISFY HOVERING TURN REQUIREMENTS AT 1.010 THE TOTAL THREE
AT TC =170, K1, ENGINE SIZED FOR TAKEDER AT T/W = 1.06 95.0 EERCEKT MILITARY FOURE SETTING E = 4000. FT, TEMPERATURE = 95.04 DEG.F. 6.C ENGINES INDERATIVE, AND 0.0 FT/HIM YERTI OF CLIME. H.P. IMSM SIZED AT 100. EERCERT CF AUX. PROPULSION CRUISE PCURE HC = 3600. Ft, Tene 91.50 DEG.E. INSE SIZEC AT 100. EESCENT OF BAIM BOTON HOVEN POWES SEC. AT B = 400c. F1, TREE = 95.04 DEG.E., 100.0 PERCENT HOVE ABSM SIZEE AT 100. IEECEST UF TALL BOTCH HOVER FOWER AT B = 4600. Pl, TERE = 95.04 DEG. P., 100.0 FERCENT HOVE ADMILIABY INTEPENDENT PROPULSION DRIVE SYSTEM FA EAK. STABLARD S.L. STATIC H.P. EAK. STANDARD S.L. STATIC H.P. ENGINE SIZEC POS CENISE AT WC = 170, RWOTS, LCHRAL PONER, STYTHER STYTHER = 91.50 DEG.P., AND 0.0 ENGISES INCERESTIVE. BAIN AND TAIL SOTOR DRIVE SYSTEM RATING TAIL BOTOR ESITE SYSTEM MATING BAIN BOTOR CEIVE SYSTEM BATING 1.761 AUI, INCEFFUDENT PRCFULSION CYCLE NO. TUEBOSHAPT PAGINE FROPULSICK DATP PRIMASY PECPULSIUM CYCLE NG. TUBEOSHAFT FEGINE 2. ENGINES 1. ENGINES Ehpepi

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PROGRAM	
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TENP.	59.0		C1/S16PA	202	3.073	0. J058	3.C13	3.C72	0.C72	0.0012	4.C72
AUG. ENG. FUCL FLC. (LES/HK)	45°		5	Calina							
Pers.	99		ЭНВ	CPPRC	2889.	2681.	0.00011	0.00011	0.00011	2848. 0.60911	2848.
ENT CODE:	jus jus		I	Ē	0.705	0.705	0.705	0.705	0.705	0.705	20.70
ACA TEXP.	550.0		TERCST 10 NE 1641	DELDCA	393.1.0	1.060	093 - 0	0.0	0.0	0.000	090.1
FCTAL FUEL FLCG (LBS/HR)	438.		TOTAL FUEL FLEB (LES/HR)	75 P DEG.							
ENG.	p= ==		FFIP. CCCE	RCTLL	۵4	c. ∢	₽ ◀	۵۹	۵.4	۵۹	a-4
PRIM TURB: (RFP:	950.0	10 HR S.	PRICE SERVICE CANAL	_							
TAS (KTS)	000	C FOR 0.10	TAS	PRIM. ENG FUEL FLOM (LBS./HR)	1432.	1,29.	1427.	1424			
8 -Jr			なした	VAC	÷÷	jė	ز,ن	نن			
WE IGHT	17643.	NO AT 1/4	HE IGHT	T.ROTCF REP	17628.	17598.	17567.	17537.	17507.	17476.	17476.
Feet Ceet Feet Feet	14.0	IEF, CR LA	1000 1000 1000 1000 1000 1000 1000 100	1.FC1CF V11F (FPS)	14.6	0.359	75.6 690.0	106.0	134.4	166.7	166.3
RANGE (N.P.)	00	KEOFF, FUL	SANGE [H.H.]	P. PC TCR RHP	2367.	23£C.	2373.	2367.	2365	23.50	2353.
TINE	0.0 0.633		TIPE	F.FCTCF VIIP	0.633	725.0	0.521	725.0	9.113	725.0	925.0
	FUEL PRESS. TURB. FPLP. TCTAL ALX. AUX. AUX. ENG. ENG. FUEL TURB. ENG. FUEL FLC. FUEL TURB. ENG. FUEL FLC. FUEL TEMP. CODE PERF (LESSION)	RANGE LSEC WEIGHT ALT: TAS TURB. ENG. FUEL TURB. ENG. ENG. FUEL TURB. ENG. ENG. FUEL FLCA TURB. ENG. FUEL FLCA	RANGE LEE WEIGHT ALT: TAS TEPP: FUTAL ALX: AUX: AUX: ENG. ENG. ENG. FUEL TOPP: CODE FLE TEPP: FUEL	RANGE 15EC WEIGHT PRESS. PRIM. FPIP. 1714L ALX. AUX. AUX. ENG. FUEL 10EB. ENG. ENG. FUEL FLCA 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	RANGE 15EC 16ES 16ES. HEIGHT ALTS 10AB 16ES FUCE FUCE 10AB 16ES FUCE FUCE FUCE FUCE FUCE FUCE FUCE FUCE	RANGE 15EC 16ES WEIGHT PRESS. 10AS 10AB ENG FUEL 10AR ENG FUEL 10AS FUEL 10AS 10AS 10AS 10AS 10AS 10AS 10AS 10AS	RANGE	RANGE FUEL ALT PRESS PRIM FNIM FNIM <t< th=""><th> RANGE FLEE /th><th>RANGE (RES) FUEL (RES) (RES) (RES) (RES) FUEL (RES) /th><th> Color Colo</th></t<>	RANGE FLEE FLEE	RANGE (RES) FUEL (RES) (RES) (RES) (RES) FUEL (RES)	Color Colo

5	CFLISE AT	17C.C KNO	-	S TAS, LIMITEC E	Y NCRMAL	ENGINE	RATING						
T PE	RANGE IN.N.)		WE 16HT	PRES.	TAS (KTS)	PALF. TURB. TEMP.	PFI CCCC CCCC	EAS (KIS)	2	CT PRIME OVER SIGMA	ALPHA 0/L (CEG)	SPEC.	g H g
N. #0108 7116 1 F S J		1. FC1CF VI IF (FFS)	1. FOTCF RMP	PROF VIIP (FPS)	PRIY.ENG FUEL FLUM ILBS/HRI		FTAP	UX. ENG. LEL FLCA (LBS/HR)	AUX TUNE TEMP.	ALX. CCOE	ACX. ENG. ENF		EN. PEP OR IMPUSI
CPFNO	CP INC	CPPAR	CPAUD	CDO	CELCOS	BELCOM	CXB	7	3	כו	*10	* aɔ	H
0. 133 725.0 4. 0304.2	2216. 8 0. 000 (49.	166.7 650.0 C.CCC265	17474.	0.01735	173.3 1239. 0.00012	1604.6	.0.003517	170.5	0.356	9,00	-5.c c.62c c.500	.10066	2545. 1119. U. 682
126.2	9262 126.0 266.0 0.000476 0.00CC48 C.CCC265	315.7 650.0 0.000265	17327.	0.31727	170.3 1295. 0.30013	1.602.8	C.000517	170.0	3.396	0.046	0.615 0.615 0.500	15001.	2534. 1119. 0.640
72 6.0	36.00	464.4 650.0 0.000269	17175.	0.01720	170.3 1281. C.0CC39	1606.9	3.0000	170.c 40c.	3.396	0.045	-5.1 C.503	.1011c	1119.
0.258	0.258 45.C0 412.1 0.000472 0.0000546 0.000026	412.7 450.0 0.000268	1703C. 0.	0.01713	170 °.1 1277 °. 0.30008	1599.1 p. 0.821 0.00515 0. CCC516	0.821		0.396	6.06.5	-5.1 3.61 0.500	17174	2512. 1119.
725.0	725.0 765.0 765.0 0.00.0 0.00 0.00 0.00 0.00 0.00 0.0		16832.	9.01 707	1273.	0.00500	0.000519	170°C	1677.6	0.0	0.617 0.500	.101. 0.037	1119.0

5	CRUISE AT SF	SPEEC FCR 9	9 PER CENT	BES 1	RANGE WITH	HEADH IND	CF C.0						
TERE	RANGE IN.P.)	FOR Semina Semin	WE IGHT	PRE S.	IAS (KIS)	ENCE ENCE ENCE ENCE ENCE ENCE ENCE ENCE	ENG.	EA (2	CT PRIME OVER SIGMA	ALPHA 5/1 (DEG)	SPEL. RAALC LAMED)	g.H.B
M.PCICE VIIP (FPS)	M. POTCR	TACTCE VIIF (FFS)	T. FOT CF RHP	PROP VTIF (FPS)	PRIMERG FLEL FLOW (LBS/HR)	8HP AUX	ETAP FFCP	LX. ENG. UEL FLOW ILBS/FRI	PUX TURE TEMP	Aux. ENG. CODE	AUX. ENG. PEHF		AUX. EAJ. BPP GA TAFUS
CP FAC	CP INE	CFPIR	CPAUD	000	CELCOS	DEL COM		7	ŝ	13	CLW	473	ğ
0.587 725.0 0.000412	0.587 61.55 0.000412 0.0000052	5 645 CCCCCCCCCC	16 79 1. 0. cooces	5000.		1517.6	C.826 0.000371	288.4	0.347	0.059	0.471 C.50C	.11ac?	1877. 569.
0.468 725.0 0.000410	42.55 1666. 0. cccc90	\$34°1 \$50°0 0°00(162	16665.	5000.		1515.6	0.826 0.000370	285.	1537.1	6.055	0.471 C.500	.1176.0	1467
0.758 725.0 J.000408	0.788 97.95 725.6 1567 3.050408 3.006688	1102.3 650.0 1 C.EOC152	1,241 1,000 0,000 0,000	5000.	1.641 1.647 0.100L.0	1513.6 0.03832	0.666370	38.4	15:347	0.058	-2.3 C.47C	.11734	1856. 247. J. 178
725.0	125.0 125.0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1220.2	1641 3.	5000.		0.00026	0.826	38.4	1536.8	C. 658	C.47C	111766	1846.
3.569 725.0 0.00405	127.93 1578. 0. cocc84	1357.¢ 650.¢ 0.300152	162 10000 0.0000	5000.		1509.7	0.000369	284.	1536.4	C-057	0.469	0.00.0	1636. 546.
12090 725.0	142.55 175.0 1569. 1569.	5 1464.6 650.0 1 C.CCC152	16158	50CC. 0.01620		1507.7	C. £2¢	38.4	1536.0	C.05 &	0.469 0.500	.11432	1826. 546. 0. 172
12 £ 20 4 C 2	260 260 260 260 260 260 260 260 260 260	1544.4 650.0 C. CCC1152	16695.	50CC.		1506.8	C.824 0.000348	38.4	1535.7	0.056	0.468	11841	1822.

SECONDARY CONTINUES CONTINUES (SECONDS)

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	1	Con in Account	7	1.949. 2.554	1924.	1362.		<u>.</u>	1. 46. . 96.	1625.	100 co		
	68446 (FFL)	15	•	2.3 1.3	1.1	6.4	£.5 £.69	, 7.3	£.9 6.007	5.0	5.3	6.20	7 7
	2 / S		A CO	0-23 0-835 0-500	-2 -0 -0 -30 -30 -30			0.641		-2.3 0.844 C.360	0.846		
	200		5	8-	-	200	930	190	0.00	58-	6.970	c.q71	5.072
	7	\$55 500 500 500 500 500 500 500 500 500	5	0.00	3-146	3.190	35.167	00183	1816.	9.105	1856.0	356.0	0.187
	2	LE FEST	•	*:	75.3 C.5.3	3.3	13:1	15.2	451	73.0	74.5	7. 20.	74.3
ENGINE ROT		300	5	c. &ce 332	C.2CC333	0.0000	C. 22.C 0.000342	C.82C 0.000343	0.00034	0.00352 C.00352	C.0CC353	0.000361	3
Ž.	2300	52	DEL COM	1856.0	1.056.0	0.0000.0	1.00062	1055.0	1#56.0 0.00C71	1.000.0	1854.0	1856.0	
	IASs.	FUEL 4. EN.	DELCOS	76. 896. 0.33003	0.00000	16.100.00	9.00000	7. 2. 2. 2. 3. 4. 5. 5. 5. 5. 5. 5. 5. 5. 5. 5. 5. 5. 5.	77.4 6.30001	78.4 832. 6.30001	821.0001.0	79 1 61 1 6 30002	4.67
		24.00 26.00 26.00	93	0.30630	500.	1360.0	1500.0	2000.	2500.	3000.0	35.00.	.0054	.500.
The need Pental	LE 16-1	F. FOTCS	grad)	14882. 9.000011	16975. 0.000011 0	16 fe f. 6.3005 ii a	1686g. 0. C300i2	1685 ;- 0. COOCIE	1684 5. 0. C3061.	1683£. 0. COOCI? 0	1682¢.	16817.	16657.
15 55 CE 5 32 35 35 35 35 35 35 35 35 35 35 35 35 35		1.AC1C6 1	*****	140.000	7.8.0 \$40.0 0.000.0	135.5	######################################	2:057	355.5	450.0 450.0 1.000.0	1.015	# # # # # # # # # # # # # # # # # # #	# 10 # 10 # 10 # 10
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<u>ਵ</u> ਹ	### ### ### ### ######################	7. 40130 ×	£) 04443	25.4.00 C. 60.00 C. 6	0.444 725.3 C. CCC 153 0.	0.503 725.0 0.00015+ 0.	92 12 92 000 130 0.	32528 3.cco152 0.	9223 0.000157 v.	9,541 0.0001to o.	92351 0.000161 0.000161	92 £43 6. 600163 0.	9:574

			CI75 169A	COC	J.C66	4.068	0.048 J. UCL?	0.058 J.006£	0.068 6.0068	4.066 0.3068	J. 0666	0.068 0.0063	0.068 J. 0068	0.0068	0.0064	0.067 6.066
			5	Called	0 - 1056 0-11 C71	C.1 058	Itomico	0.00010	0.10147	0.0000.0	L.CC87	0.0001	0.0068	9 . COS	590770	C. CO86
		•	Ē	CPRC	0.00011	0.00011	:1633.c	0.65311	0.000 ii	3.6511: 3.65011	0.00011	2457	0.00011	0.03011	0.96311	c. 66911
			£	E	0.139	0.799	0.703	0.709	0.709	0.733	0.709	0.709	0.709	0.709	0.709	0.709
			TPUST IC WE IGHT	06190	1 . C60	0.5.0	0,000	3,0000	0.000	090 0.0	090.0	0,000	1.060	0.00	0.5°60	0.0
			TOTAL FUEL FLCG ILES/HR)	16.0 06.6.	1350.	1387.	1385. 455.	55.4	1380.	1378.	1376.	1374.	1371.	1364.	1367	1367. 55.4
			FRIT GAG CCOE	1000 CCCE	۵.	4	44	•4	6 <	u <	u <	a. «	•4	44	u. <	٨.
	•	O HRS.	Parit Tean Farit	AUX.ENG FUEL FLOW (LES/HR)	1633.1	1631.9	1630.6	1629.4	1628.2	1627.0	1625.8	1624.6	1623.4	1622.2	162830	1621.0
	AFES. 5000. 1000.	C FCA 0.200	TAS (KTS)	PRIN.ENG FUEL FLUA (1.05/HR)	1296.3	1255.	1253.	1591	1288.	1286.	0.0 1284.	12 62.	12 79.	1299	1275.	1275.
-	MEIGHT (185.) 16059. 16059.	* 1.0¢C	PRES.	Sec.	1000	.; ;;	3 3 3 3	1300.	1300.	.; ;;	1000.	300E	1000.	.00C1	.3 ₀₀₁	1000
1000. F	100 M	LANG AT 1/A	WE IGHT	T. PUTOR	16099.	16071.	1 6043.	16015.	15986.	15965.	15933.	15905.	15976.	15856.	15823.	15823. 266.
HEE IC	18. 18. 18. 18. 18. 18. 18. 18. 18. 18.	HOVEF, CP LI	10E 15E 10E 10E 10E 10E 10E 10E 10E 10E 10E 10	1.5CTG9 VIIIF (FP.5)	1544.4	1572.1	1555.9	1627.6	655.3	1686.5 696.0	1716.4	1727.5 65C.0	1765.4	1756.6	1666.6	182C.2 65C.C
TRANSFER ALTITLE	1.137 CA.	TAKEDFF, HOV	ALAGE (4.F.)	4. ROTCK	156.60	156,50	15666	150.GC 2064.	150,50	150,00	1 50° CC 2027.	150.CC 2062.	1 50 co 20 co	15051	1 20285	150.00
181		1.21	11 PE	M.FCICA VIIF	1213	121:3	124.73	124.0	1:31	125.7	125.0	125.0	125.0	123.0	123:7	125.0

CHANGE FALCAL, REPCVE 1000, LE.

THE FUEL WEIGHT ALTS.

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JOHN TOWNS THE WASHING THE STATE STATE STATES AND STATES APPLIES.

	417	AUX. Eibs. BHP GK IMRUST	ž	. 1893. 555. 0.962	10.00°	1087. 55. 0.942	106? 55. 0.942	1380. 55. 0.942	1077.	1074. 55. 0.941	1070. 541	1068. 53. 0.942	1065. 53. 0.942	1061. 53.
	101 A. FLEL -10.		7 <u>0</u>	361.	36¢.	965. 0.067	4ec.0	96.0. 0.0r7	962.	961.	966.	955.	958.	951. 0.Jt7
	ALPHA D/L (CEG)	ACX FRG. PEHF.	ž	1.04.n	0.044 0.044 0.444	0.043	0.443	0.04. 0.04. 0.04.	0.043	0.043	0.043 0.043	0.04.2 C.400	0.42	0.04.2
	CT PRIME OVER SIGNA	ALX. CCOE	10	0.056	0.056	950-0	0.056	0.055	0.05	0.055	0.055	0.055	0.055	0.054 P
	7	TUX TURE:	5	1207.7	3:17£	1297.6	1207.6	1267.5	1207.5	120174	120174	1206.2	3,174	1266.2
	ESS	LX. ENG. LEL FLOM (LBS/HR)	")	155.	15.3	155.	74.5	15:5	155.	156.5	74.5	134.5	13.5	134.5
	ENG.	FIAP	CXA	C. 635	C.835 0.000183	C.835 C.000183	0.000163	0.835	C.0CC183	C. £35 0. CC0 1 £2	C.835 0.000182	0.00179	0.835°.	0.635
	ADE AND AND AND AND AND AND AND AND AND AND	BHP	DELCOM	1375.0	1374.4	1373.8	1372.2 0.0003A	1372.6	1372.0	0.00037	137C.8 0.00037	1370.5	1365.9	1369.3
	IAS (KIS)	PRIA-ENS FUEL FLUA (LBS/HR)	DELCDS	75.6 813.	75.6 812.	9.52	75.6 810.	75.4 809.	75.6 808. 0.0	75.6 0.0	75.6 806.	945.0	74.6 804.	803.
	PRES.	980P 917V 617Y	99	1000.	1000.	10C0.	1000.	1000.	1000.0	1000.0	1000.0	1000.0	1000.	1000.0
۶.	LE IGHT	1. POTOR	CPNUD	14 E2 3 . 5 5 7 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5	14774. 573 0. COCCCS	14 724. 575 0. cooccs	1467£. 0. cooces	14636.	14581.	14533.	14485. 0. cooccs	14437.	14385.	14341.
C.SCC PR	12E 13E 185	1.PCTCR VIIP (FFS)	CFF AR	1820.2 650.0 C.5CC33	1666.6 650.0 C.CCC033	1516.5 650.0 0.000033	1565.2	2013.4	2041. ¢ \$50.00 0.000033	2169.7 650.0 C.coco32	650333.3 0.00033	2265.7	2253.7	2301.6
ITER FOR	RANGE (N. W.	A. POTCR	CP INC	15c.co 3c6.	15C.00 5C3. 0. 00C160	15C.30 \$£00. 0.00C159	156.00	156.00	156.36	15C+00 ERE 0.00C155	15C.03 8E5 0.0CC154	15C 00 6E3 0.00C155	156,00	150.00
נט	11 11 12 13 13 13 13 13 13 13 13 13 13 13 13 13	M.RCTCR VIIP (FPS)	CPFAC	12 3 47 6. 0001 59	12 257 72 250 0. CCC 1 50	125.0	12457 C. CC0150	125.0	125.0 6.000150	125.0	12657	125.0	12 250 0.000149	125.0

	EFPRI	_		1469,	1429	.6861	1348	1 364
	9	AUX. cki. BiP Ck ingus!	æ	1505. 1469. J. 543	124. 0.546.	1864. U.945	1947 1.946.2	1827.
	CEC)	0.5	.	132	0.11	1C.6	16.3	10.0
	ALPHA O/L (CEG)	FLE.	2	-2.6 0.838 C.400	-2.6 C.840 G.400	-2.6 0.841 0.490	-2.6 0.843 C.400	0-2.5
	CVER CVER SIGNA	COC.	5	0.055	0.055	0.056	6.657	6.95
	2	TCA .	3	2.165 1856. C	1956.6	3-171	3.171	1856.0
	FAS	ux. ens. uel fich iles/ha)	,	70.5	65.3	73.4	66.6	69.6
THE BAT	CCOE	FFCF	CXR	C.82C	0.820	T C.82C 0.0C0326	1 C.0c0327	C. C. C. 2.26
THE FLE	TRIA.	AUX	CEL COS	1856.0 T C. 82C	1856.0	1856.0	1856.0	1856.0
NITH PAXIMUP RIC AT NEMBL ENGINE DATE FOR PAIL THE HORIZONIAL CEMPONENT OF THE FLIGHT PATH	IAS (KTS)	PRIN.ENG FLEL FLCM (LOS/HR)	GELCOS	374.5	365.0	12.5 852. G.J	72.5 842.	72.5 631.
XIHUP RI	PRES. ALT:	PROF VIIP (FP 5.)	8	1000.	1500.	20C0.	25 60.	3000.
	HE ICHT	A 1. 601 0 F	C PNUD	14341. c. coocci	14336.	14331. 2000. 51. cooocs c.00 £20	14326.	14 32 1.
CCC. Fl.	PERE CONTRACT CONTRAC	1.5CTC 5115 (FFS)	CFPAR	23C1 • £	7,5000.0	2311.6 650.0 0.000066	2:14.7 650.0 0.000657	2321.5
CLEM TC 3CCC. FT.	RANGE (N. P.)	*. ROTCR RHP	CP INC	156.03	150.41	156.83	151.28	1.671 151.73 2321.5 725.0 947 656.0
10	1 1 2 E	M. RCICR VIIP (EFS)	CPFRC	12847 0.350	125.3 C.000147	125.6 125.6 0.330149 0.306166 C.CGCG56	125.0 0.00145	725.0

	411	AUX. ENG. BPP UX HRCSI	3	1613. 672. 0.723	1605. 072. 0.721	1557. 071. 0.718	1590. 679.	1582. 670. 0.713	1575. 669. 0.711	1568. 568. 5. 709	1561. % 7	1553. u67:	1546. 606. 0.700	1549. 905. 3.647
	SPEC. RANGE (ARPP)		400	11017	.118.2	11.867	0.007	11411.	11541.	.11566	05511.	.12015	12238	.12060
	ALPHA 071 (066)	AUX. FEFF	43	6.541 0.500	C.5.4.	-2.e C.546 C.506	2 5 0 546 0 500	C.514.9	0.544	-3.0 5.544	0.30		6.500 1.400	-3.1 0.542 C.500
	T PRIME CVER SIGPA	CCC.	5	5.044	200	0.043	0.0	6.042	200	8-	96	84	0.039	0.039
) 1	ALX. TURE. TEMF.	5	1509.1	1608.7	0.345	1607.7	1667.2	1606.8	1666.3	1,349	3,349	0.349	1604.5
	EAS (KIS)	LX. ENG. LEL FLEW (LBS/HR)	7	335.	143.6	143.6	143.6	143.6	143.6	143.6	143.6	163.6	3326	332.
OF C.C	PRIK ENG. CCDE	FILE	CXB	0.82¢ 0.0¢¢2333	C.826	0.000273	0.3C0272	0.826	0.826 C.CCC212	0.00021	6.E251 C.CCC211	0.000211	0.000271	0.826
	PRICE TENES (R)	AUX	DELCOM	1,60.1	1458.7	0.00643	1455.9	1454.6	0.00630	1451.9	1450.6	1445.3	0.00613	3.00610
RANGE WITH HEADWING	IAS (KTS)	PRIM-ENG FUEL FLOW ILBS/HRI	BELCUS	150.1	150.1 934. 0.30331	150.1 932. 0.30031	150.1 929. 0.0000.3	150.1 927. 0.00000	150 1 925. 0.00000	150.1 522.0000.0	150.1 929. 0.00000	1.50.1 91.4.0	1.50.1 916: 0.00000	150.1 914. C. 30003
BES 1	PRES. ALT: (FT)	PROF VIIP FPS1	89	3000.	33 60. 0.31 43H	3000.	3060.	3000.	3000.	3000.	3000.	3000.	3000.	3000.
PER CENT	WE IGHT	I. FOTCF	CPNUO	14321. 106. 0. cocc41	14194.	14067. 0. cooc4c	13941.	1341 5.	13685. 55. 0.000038	13562.	13436.	13313.	131 ge. 9 e. 0. cooc36	130 JE.
EEC FCR 99		T.FCTCP VIIP FPCJ	CPFAR	2321.5 656.0 C.c.c.c.14	2448.5	2575.5	21002.5	2828.1 650.0 0.000113	2553.5 656.6 6.000113	3675.6	3264.5 650.0 C.000113	\$ 055 \$ 055	3454.5 550.0 0.000113	3565.1 650.0 0.000112
HSE AT SP	RANGE (N.F.)	r. rcick	CP INC	151.73 1267 0.066650	156.73 1360. 0. cccc49	16]; 73 1 3 53. 0. cccc46	194.73	21 13.73	22453 1132 0. COCC44	241,13	256.73	271.73	286.73 1305. 0. CCCC40	30c,00 1259 0.00cc39
CFU151	11. 11. 12. 13.	7 ~ . Func Sup Sup	CP P90	124.0	12571 C. CCC36C	2.071 725.5 0.000355	2. 1. 1. 1. 5. 5. 5. 5. 5. 5. 5. 5. 5. 5. 5. 5. 5.	2: £71 0: 000356	22378 6.660355	2:471 725:0 3.600354	2.571 725.0 0.000353	2.6.70 5.000.55 6.000.55	2.770 725.C 0.000351	725.0 0.cc635c

FUEL	
FESERVE F	
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C.250	
FOR	
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*	AUX. E.AG. BEP Un Thrust	ē	.1022. J. 943	1019. 0.942	1017. 0. 542	1014. 0.942	1011. 0.942	1.108. 0.943
FLEL FLU.	Ψ.3	3	435.	835. 0.cc?	434. 0. uC?	833. 0.0C7	632.	831. 0.00?
ALPHA D/L (CEG)	PEKG.	מי	2-7-3	3-7-3	0-5.3	0-5.3	0-5-3	-2.2 0.0 6.400
T PRIME CVER SIGNA	ACX. CCDE.	5	C.C53	0.052	0.052	0.052	6.052	C.052
2	ACK ACK ACK	5	0.17C 852.1	0.170	0.17C 352.1	9:27	852.1	0.16E 852.1
EAS KIS	JX. ENG. LEL FLCW (LBS/HR)	7	78.	16.3	69.9	69.5 7E.	76.9	69.0 7e.
PFIF CCCE	ETAP C	CXB	C. ECC264	C. £35 0.000264	0.000263	C.835	0.835 c.0c0263	0.835 c.cc0258
TERES.	PHP	DELCOM					1359.2	
IAS	PRIG.ENS FUEL FLOW (LBS/HR)	DELCDS	73-1 754.	73.1 0.0	73.1	73.1	73.1 755.	754.
PRES.	PROF VILP (FPS)	993	3000.	3000.	3000.	3000.	30C0.	3000.
WE IGHT	_:«	CPNUO			12994. 0. COOCCE	12953. 0.00000E	1291]. 53. 0. COOCCE	12865. 9.000čči
FUEL FEEL FEEL S	1.2CTCP VIIP (FFS)	CPPAR	2565.1 666.0 5 0.00066.0	3 3456.5 450.0 5 C.CCC045	3648.6	2650.3 5.02.5 6.03.5 C.CCCC4!	3731.5	3773.5 £56.0 C.CCC644
RANGE	A.ROTCR RHP	CP INC	30c.30 641. c. 00c145	25.0 300.00 .25.0 63%	125.0 125.0 1.000148 0.000144 0.000045	30C 00 E33.	325.0 725.0 5.000148 0.000142 (.00045)	22.0 306.30 3733.5 628. E50.0 .300147 0.000144 C.CCC044
T I'VE	M. RCTOR VIED	CPFFO	2. £55 30C,30 725.0 E41. G. CCC14E C. 30C146	2.505 725.0 C. C0014E	225.3 226.00148	3, 639 725, 0 0, 000 149	3.555 725.0 3.000148	3.169 724.0 0.000147

ISSICN FLEL RECLIPEC = 3545.08 ESERVE FUEL RECLIREC = 206.46 OTAL FLEL RECLIREC = 3773.53

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